CS 4644 / 7643-A DEEP LEARNING: LECTURE 3 DANFEI XU (SLIDE ADAPTED FROM PROF. ZSOLT KIRA)

- Linear Classifier (cont.)
- SVM / Hinge Loss
- Softmax Classifier and Cross-Entropy Loss
- Gradient Descent



Recap:

Supervised Learning

- Train Input: $\{X, Y\}$
- Learning output:

$$f: X \to Y$$
, e.g. $P(y|x)$

Unsupervised Learning

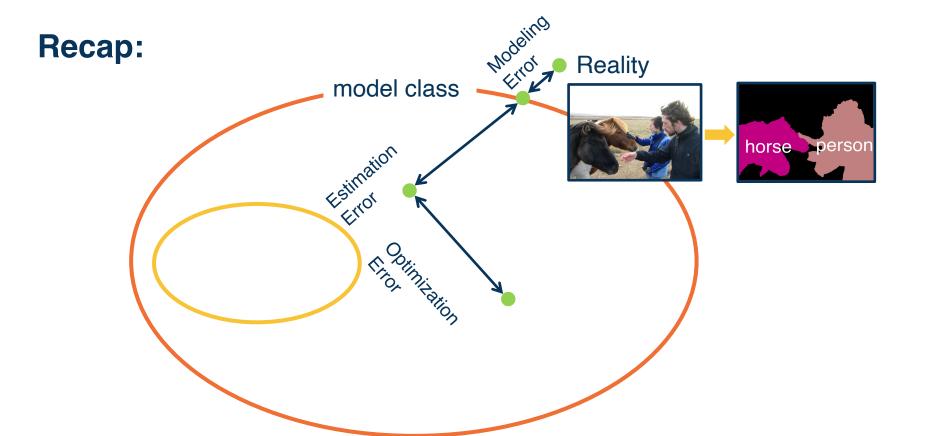
- Input: {X}
- Learning output: P(x)
- Example: Clustering, density estimation, etc.

Reinforcement Learning

- Supervision in form of reward
- No supervision on what action to take

Very often combined, sometimes within the same model!

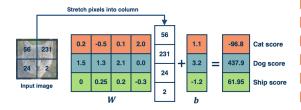




Recap:

Algebraic Viewpoint

$$f(x, W) = Wx$$



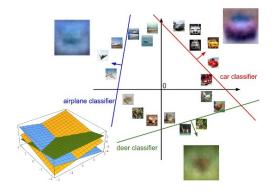
Visual Viewpoint

One template per class



Geometric Viewpoint

Hyperplanes cutting up space



This time:

$$f(x,W)=Wx$$







airplane	-3.45	-0.51	3.42
automobile	-8.87	6.04	4.64
bird	0.09	5.31	2.65
cat	2.9	-4.22	5.1
deer	4.48	-4.19	2.64
dog	8.02	3.58	5.55
frog	3.78	4.49	-4.34
horse	1.06	-4.37	-1.5
ship	-0.36	-2.09	-4.79
truck	-0.72	-2.93	6.14

- 1.Define a **loss function** that quantifies our unhappiness with the scores across the training data.
- 2. Come up with a way of efficiently finding the parameters that minimize the loss function. **(optimization)**



Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:







cat car frog 3.2

1.3

2.2

5.1

4.9

2.5

-1.7

2.0

-3.1

High Loss

Low Loss

High Loss

A **loss function** that tells how good the current classifier is

Given a dataset of examples:

$$\{(x_i, y_i)\}_{i=1}^N$$

Where x_i is image and y_i is (integer) label

Loss over the dataset is a sum of loss over examples:

$$L = \frac{1}{N} \sum L(f(x_i, W), y_i)$$



Given an example (x_i, y_i) where x_i is the image and where y_i is the (integer) label,

and using the shorthand for the scores vector: $s = f(x_i, W)$

Notation: s_{y_i} is the **score** given by the classifier for the correct label class of the i-th example (y_i)

the SVM loss has the form:

$$L_{i} = \sum_{j \neq y_{i}} \begin{cases} 0 & \text{if } s_{y_{i}} \geq s_{j} + 1 \\ s_{j} - s_{y_{i}} + 1 & \text{otherwise} \end{cases}$$
$$= \sum_{i \neq y_{i}} max(0, s_{j} - s_{y_{i}} + 1)$$

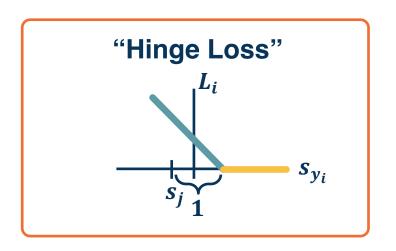
Given an example $(x_{i,}y_{i})$ where x_{i} is the image and where y_{i} is the (integer) label,



and using the shorthand for the scores vector: $s = f(x_i, W)$

the SVM loss has the form:

$$L_{i} = \sum_{j \neq y_{i}} \begin{cases} 0 & \text{if } s_{y_{i}} \geq s_{j} + 1 \\ s_{j} - s_{y_{i}} + 1 & \text{otherwise} \end{cases}$$
$$= \sum_{j \neq y_{i}} max(0, s_{j} - s_{y_{i}} + 1)$$



Given an example (x_i, y_i) where x_i is the image and where y_i is the (integer) label,

and using the shorthand for the scores vector: $s = f(x_i, W)$

the SVM loss has the form:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

= max(0, 5.1 - 3.2 + 1) + max(0, -1.7 - 3.2 + 1)

= max(0, 2.9) + max(0, -3.9)

= 2.9 + 0

= 2.9

Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:







cat

car

frog

Losses:

3.2

5.1

-1.7

2.9

1.3

4.9

2.0

2.2

2.5

-3.1



Given an example (x_i, y_i) where x_i is the image and where y_i is the (integer) label,

and using the shorthand for the scores vector: $s = f(x_i, W)$

the SVM loss has the form:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

 $= \max(0, 1.3 - 4.9 + 1) +$

max(0, 2.0 - 4.9 + 1)

 $= \max(0, -2.6) + \max(0, -1.9)$

= 0 + 0

= 0

Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:







cat

3.2

car

5.1

frog

-1.7

Losses:

2.9

1.3

4.9

2.0

0.0

2.2

2.5

-3.1



Given an example (x_i, y_i) where x_i is the image and where y_i is the (integer) label,

and using the shorthand for the scores vector: $s = f(x_i, W)$

the SVM loss has the form:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

$$L = (2.9 + 0 + 12.9)/3$$
$$= 5.27$$

Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:







2.2

2.5

-3.1

cat

car

frog

Losses:

3.2

5.1

-1.7

2.9

1.3

4.9

2.0

12.9



Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

Q: What happens to loss if car image scores change a bit (e.g., \pm 0.1)?

No change for small values







cat	3.2
	F 4

1.3

4.9

2.0

2.2

2.5

-3.1



Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

C

3.2





2.5

Q: What is min/max of loss value?

[0,inf]

cat

car

5.1

frog -1.7

1.3

3 2.2

4.9

2.0 **-3.1**



Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:

$L_i = \sum_{j \neq y_i}$	$max(0, s_j - s_{y_i} + 1)$
---------------------------	-----------------------------

0 9





Q: At initialization W is close to 0 so all s ≈ 0. What is the loss?

cat

3.2

1.3

2.2

num_class - 1

car

5.1

4.9

2.5

frog

-1.7

2.0

-3.1



Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:

$$L_i = \frac{1}{C} \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$





Q: What if we used mean instead of sum?

cat

3.2

1.3

2.2

No difference Scaling by constant car

frog

5.1

-1.7

4.9

2.0

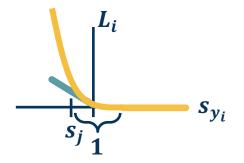
2.5

-3.1



$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)^2$$

Q: What if we used squared hinge loss?



- Smooth loss around hinge
- Sensitive to outliers (larger penalty)

Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:







cat	3.2	1.3	2.2
car	5.1	4.9	2.5
frog	-1.7	2.0	-3.1



$$L_i = \sum_{j
eq y_i} \max(0, s_j - s_{y_i} + 1)$$

```
def hinge_loss_vec(x, y, W):
    """

x (d): input example vectors
y (int): class label
W (C x d): weight matrix
    """

scores = W.dot(x)  # calculate raw scores
margins = np.maximum(0, scores - scores[y] + 1) # calculate margins s_j - s_{yi} + 1
margins[y] = 0 # exclude yi from the loss sum
loss_i = np.sum(margins). # sum across all j (classes)
return loss_i
```



$$egin{aligned} f(x,W) &= Wx \ L &= rac{1}{N} \sum_{i=1}^N \sum_{j
eq y_i} \max(0,f(x_i;W)_j - f(x_i;W)_{y_i} + 1) \end{aligned}$$

E.g. Suppose that we found a W such that L = 0.

Q: Is this W unique?

Let's look at an example



Suppose: 3 training examples, 3 classes. With some W the scores f(x,W)=Wx are:







cat **3.2** car 5.1 frog -1.7

1.3 **4.9** 2.0 2.2 2.5 -3.1

Before:

$$= \max(0, 1.3 - 4.9 + 1) + \max(0, 2.0 - 4.9 + 1) = \max(0, -2.6) + \max(0, -1.9) = 0 + 0 = 0$$

With W twice as large:

```
= \max(0, 2.6 - 9.8 + 1) 
+ \max(0, 4.0 - 9.8 + 1) 
= \max(0, -6.2) + \max(0, -4.8) 
= 0 + 0 
= 0
```



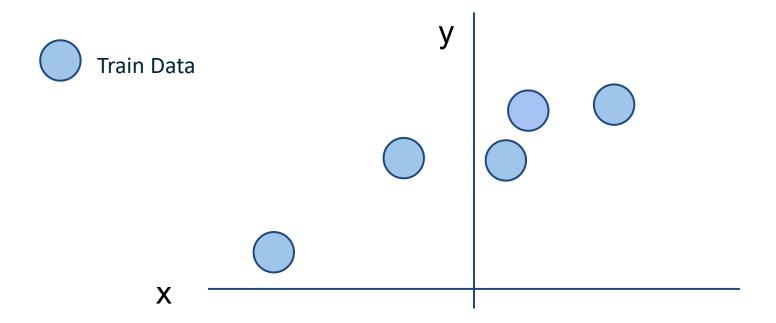
$$egin{aligned} f(x,W) &= Wx \ L &= rac{1}{N} \sum_{i=1}^N \sum_{j
eq y_i} \max(0,f(x_i;W)_j - f(x_i;W)_{y_i} + 1) \end{aligned}$$

E.g. Suppose that we found a W such that L = 0. Q: Is this W unique?

No, 2W also has L=0 How do we choose between W, 2W, and 1e+7W?

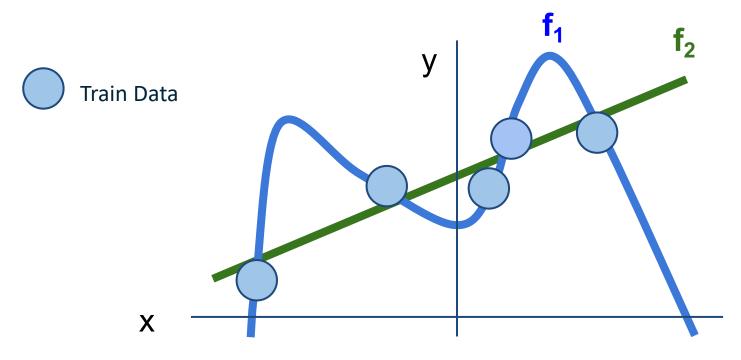


Regularization intuition: fitting a polynomial function



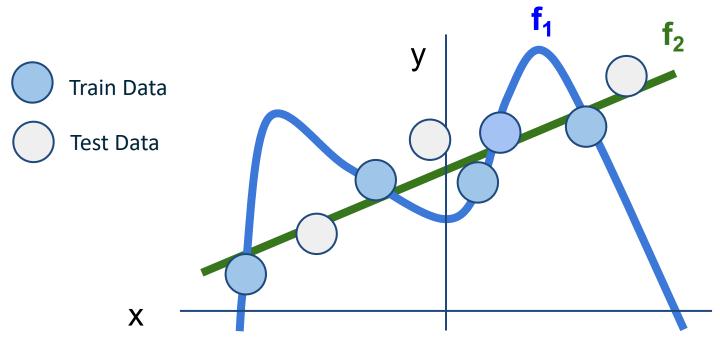


Regularization intuition: fitting a polynomial function





Regularization intuition: fitting a polynomial function



Regularization balances the simplicity of the function and loss, so we don't overfit to the noises in the data



Regularization

$$L(W) = \underbrace{\frac{1}{N} \sum_{i=1}^{N} L_i(f(x_i, W), y_i) + \lambda R(W)}_{i=1}$$

Data loss: Model predictions should match training data

Regularization: Prevent the model from doing *too* well on training data



Regularization

$$\lambda$$
 = regularization strength (hyperparameter)

$$L(W) = \underbrace{\frac{1}{N} \sum_{i=1}^{N} L_i(f(x_i, W), y_i) + \lambda R(W)}_{i=1}$$

Data loss: Model predictions should match training data

Regularization: Prevent the model from doing *too* well on training data

Simple examples

L2 regularization: $R(W) = \sum_{k} \sum_{l} W_{k,l}^2$

L1 regularization: $R(W) = \sum_{k} \sum_{l} |W_{k,l}|$

Elastic net (L1 + L2): $R(W) = \sum_k \sum_l \beta W_{k,l}^2 + |W_{k,l}|$

More complex (DNN-specific):

Dropout

Batch/layer normalization

Stochastic depth, fractional pooling, etc

Regularization: Implement a simple L2 regularizer

$$L(W) = \frac{1}{N} \sum_{i=1}^{N} L_i(f(x_i, W), y_i) + \lambda R(W)$$

```
def 12_regularized_hinge_loss(x, y, W, reg_coeff):
    data_loss = 0
# calculate dataset loss
    for i in range(x.shape[0]):
        data_loss += hinge_loss_vec(x[i], y[i], W)

# calculate weight regularization loss
    reg_loss = np.sum(np.square(W)) * reg_coeff

return data_loss + reg_loss
```

What if we want probabilities?





^{*}Technically we can get probability from SVM classifiers too, see Platt scaling



probabilities / logits

Want to interpret raw classifier scores as probabilities

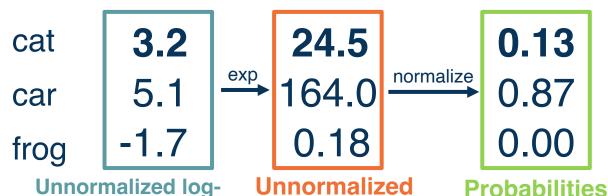
$$s = f(x_i; \theta)$$

 $p_{\theta}(Y = y_i | X = x_i) = \frac{e^{s_{y_i}}}{\sum_{j} e^{s_j}}$

Softmax Function

Probabilities must be >= 0

Probabilities must sum to 1



How do we compute the loss?

Adapted from from CS 231n slides



probabilities



Want to interpret raw classifier scores as probabilities

$$s = f(x_i; \theta)$$

$$p_{\theta}(Y = y_i | X = x_i) = \frac{e^{s_{y_i}}}{\sum_j e^{s_j}}$$
 Softmax Function

We maximize the probability of $p_{\theta}(y_i|x_i)!$

cat
car
5.1
frog
Unnormalized logprobabilities / logits

0.13
0.87
0.00
Predicted
Probs

Finding a set of weights θ that maximizes the probability of correct prediction: $\underset{\theta}{\operatorname{argmax}} \prod p_{\theta}(y_i|x_i)$

This is equivalent to:

$$\underset{\theta}{\operatorname{argmax}} \sum \ln p_{\theta}(y_i|x_i)$$

$$L_i = -\ln p_{\theta}(y_i|x_i) = -\ln \left(\frac{e^{s_{y_i}}}{\sum_{j} e^{s_j}}\right) = -\ln(0.13)$$

1. Maximum Likelihood Estimation (MLE):

Choose weights to maximize the likelihood of observed data. In this case, the loss function is the **Negative Log-Likelihood (NLL)**.

(softmax)



Want to interpret raw classifier scores as probabilities

$$s = f(x_i; \theta)$$

$$p_{\theta}(Y = y_i | X = x_i) = \frac{e^{s_{y_i}}}{\sum_j e^{s_j}}$$
 Softmax Function

2. Information theory view





Want to interpret raw classifier scores as probabilities

$$s = f(x_i; \theta)$$

$$p_{\theta}(Y = y_i | X = x_i) = \frac{e^{s_{y_i}}}{\sum_j e^{s_j}}$$
 Softmax Function

2. Information theory view

 cat
 3.2
 softmax
 0.13

 car
 5.1
 0.87

 frog
 -1.7
 0.00

 -1.7
 0.00

 -1.7
 0.00

 -1.7
 0.00

 -1.7
 0.00

 -1.7
 0.00

Unnormalized logprobabilities / logits Probs (softmax) maximize agreement

Cross Entropy: $H(p,q) = -\sum p(x) \ln q(x)$

Cross Entropy Loss -> NLL

$$H_{i}(p, p_{\theta}) = -\sum_{y \in Y} p(y|x_{i}) \ln p_{\theta}(y|x_{i})$$
$$= -\ln p_{\theta}(y_{i}|x_{i})$$

$$L = \sum H_i(p, p_\theta) = -\sum \ln p_\theta(y_i|x_i) \equiv NLL$$

1.00

0.00

0.00

Correct probs



NLL and CrossEntropy are different loss functions in PyTorch!

CROSSENTROPYLOSS

CLASS torch.nn.CrossEntropyLoss(weight=None, size_average=None, ignore_index=- 100, reduce=None, reduction='mean', label_smoothing=0.0) [SOURCE]

logits as input (the function will apply softmax & log on top)

NLLLOSS

CLASS torch.nn.NLLLoss(weight=None, size_average=None, ignore_index=- 100, reduce=None, reduction='mean') [SOURCE]

Expects log probabilities as input (do it yourself!)





Want to interpret raw classifier scores as probabilities

$$s = f(x_i; \theta)$$

$$p_{\theta}(Y = y_i | X = x_i) = \frac{e^{s_{y_i}}}{\sum_j e^{s_j}}$$
 Softmax Function

Cross-entropy loss:

$$L_i = -\log(p_{\theta}(y_i|x_i))$$

Q: What is the min/max of possible loss L_i?

Infimum is 0, max is unbounded (inf)





Want to interpret raw classifier scores as probabilities

$$s = f(x_i; \theta)$$

$$p_{\theta}(Y = y_i | X = x_i) = \frac{e^{s_{y_i}}}{\sum_j e^{s_j}}$$
 Softmax Function

Cross-entropy loss:

$$L_i = -\log(p_{\theta}(y_i|x_i))$$

Q: At initialization all s will be approximately equal; what is the loss?

Log(C), e.g. $log(3) \approx 1.1$

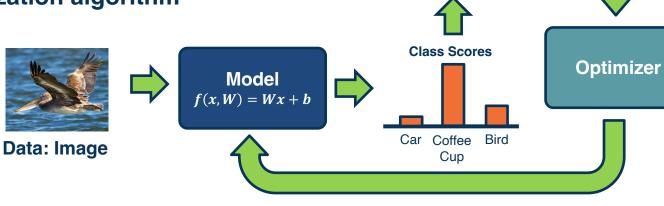


Loss functions: SVM and Softmax Classifier

- Loss function: performance measure to improve
 - Find weights that better satisfies the objective
- Multiclass SVM Classifier
 - Predicts class score
 - Hinge loss: "maximum margin" objective: $L_i = \sum_{j \neq y_i} max(0, s_j s_{y_i} + 1)$
- Regularization
 - Prevent overly complex function that only works well on the training set
- Softmax Classifier
 - Predicts class probabilities
 - NLL and Cross Entropy Loss



- Input (and representation)
- Functional form of the model
 - Including parameters
- Performance measure to improve
 - Loss or objective function
- Algorithm for finding best parameters
 - Optimization algorithm



Class Scores

Bird

Car Coffee

Cup

Loss Function

Strategy #1: A first very bad idea solution: Random search

```
# assume X train is the data where each column is an example (e.g. 3073 x 50,000)
# assume Y train are the labels (e.g. 1D array of 50,000)
# assume the function L evaluates the loss function
bestloss = float("inf") # Python assigns the highest possible float value
for num in xrange(1000):
  W = np.random.randn(10, 3073) * 0.0001 # generate random parameters
  loss = L(X train, Y train, W) # get the loss over the entire training set
  if loss < bestloss: # keep track of the best solution
    bestloss = loss
    bestW = W
  print 'in attempt %d the loss was %f, best %f' % (num, loss, bestloss)
# prints:
# in attempt 0 the loss was 9.401632, best 9.401632
# in attempt 1 the loss was 8.959668, best 8.959668
# in attempt 2 the loss was 9.044034, best 8.959668
# in attempt 3 the loss was 9.278948, best 8.959668
# in attempt 4 the loss was 8.857370, best 8.857370
# in attempt 5 the loss was 8.943151, best 8.857370
# in attempt 6 the loss was 8.605604, best 8.605604
# ... (trunctated: continues for 1000 lines)
```

Lets see how well this works on the test set...

```
# Assume X_test is [3073 x 10000], Y_test [10000 x 1]
scores = Wbest.dot(Xte_cols) # 10 x 10000, the class scores for all test examples
# find the index with max score in each column (the predicted class)
Yte_predict = np.argmax(scores, axis = 0)
# and calculate accuracy (fraction of predictions that are correct)
np.mean(Yte_predict == Yte)
# returns 0.1555
```

15.5% accuracy! not bad! (SOTA is ~99.7%)

Adapted from from CS 231n slides



Given a model and loss function, finding the best set of weights is a **search problem**

 Find the best combination of weights that minimizes our loss function

Several classes of methods:

- Random search
- Genetic algorithms (population-based search)
- Gradient-based optimization

In deep learning, **gradient-based methods are dominant** although not the only approach possible

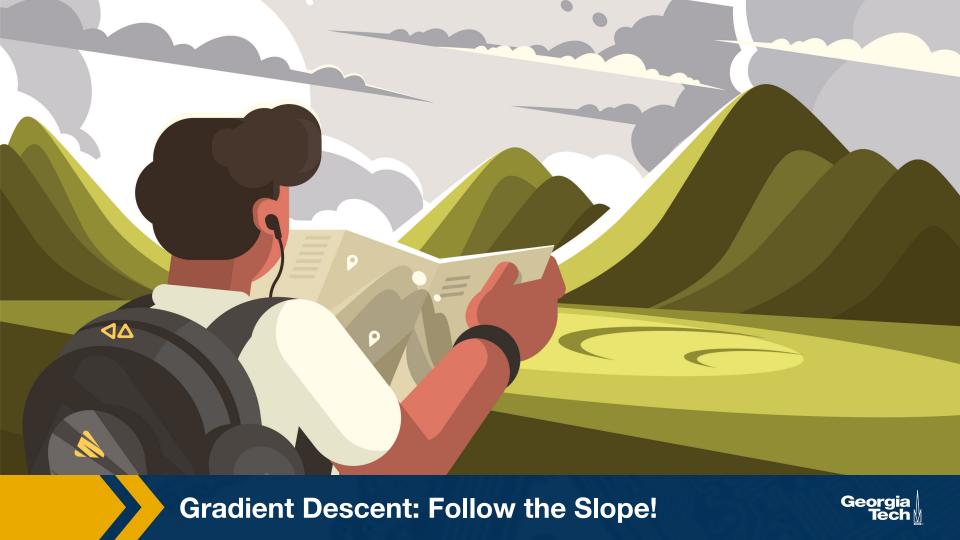
W_{11}	w_{12}	• • •	w_{1m}	b1]
w_{21}	W_{22}	• • •	w_{2m}	b2
	W_{22}		w_{3m}	b 3



Loss

- Calculate the gradients of a loss function with respect to a set of parameters (w's).
- 2. Update the parameters towards the gradient direction that minimizes the loss.

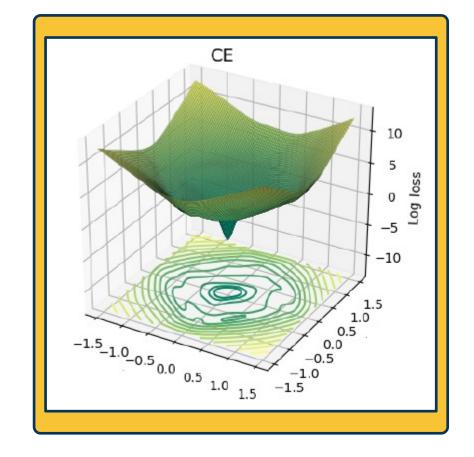




As weights change, the gradients change as well

 This is often somewhatsmooth locally, so small changes in weights produce small changes in the loss

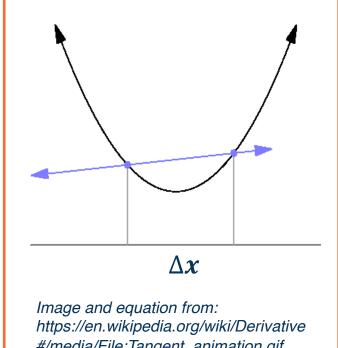
We can therefore think about iterative algorithms that take current values of weights and modify them a bit



We can find the steepest descent direction by computing the derivative:

$$f'(a) = \lim_{h \to 0} \frac{f(a+h) - f(a)}{h}$$

- **Gradient** is multi-dimensional derivatives
- Steepest descent direction is the **negative gradient**
- **Intuitively:** Measures how the function changes as the argument a changes by a small step size
- In Machine Learning: Want to know how to minimize loss by changing parameters
 - Can consider each parameter separately by taking partial derivative of loss function with respect to that parameter



#/media/File:Tangent_animation.gif



current W:

[0.34,-1.11, 0.78, 0.12, 0.55, 2.81, -3.1, -1.5, 0.33,...] loss 1.25347

gradient dW:

```
[?,
?,
?,
?,
?,
?,
?,...]
```

current W:	W + h (first dim):	gradient dW:
[0.34,	[0.34 + 0.0001 ,	[?,
-1.11,	-1.11,	?,
0.78,	0.78,	?,
0.12,	0.12,	?,
0.55,	0.55,	?,
2.81,	2.81,	?,
-3.1,	-3.1,	?,
-1.5,	-1.5,	?,
0.33,]	0.33,]	?,]
loss 1.25347	loss 1.25322	

current W:	W + h (first dim):
[0.34,	[0.34 + 0.0001 ,
-1.11,	-1.11,
0.78,	0.78,
0.12,	0.12,
0.55,	0.55,
2.81,	2.81,
-3.1,	-3.1,
-1.5,	-1.5,
0.33,]	0.33,]
loss 1.25347	loss 1.25322

gradient dW:

[-2.5,
?,
?,
$$(1.25322 - 1.25347)/0.0001$$
$$= -2.5$$
$$\frac{df(x)}{dx} = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$
?,
?,...]

current W:	W + h (second dim):	gradient dW:
[0.34,	[0.34,	[-2.5,
-1.11,	-1.11 + 0.0001 ,	?,
0.78,	0.78,	?,
0.12,	0.12,	?,
0.55,	0.55,	?,
2.81,	2.81,	?,
-3.1,	-3.1,	?,
-1.5,	-1.5,	?,
0.33,]	0.33,]	?,]
loss 1.25347	loss 1.25353	-,1

current W:	W + h (second dim):
[0.34,	[0.34,
-1.11,	-1.11 + 0.0001 ,
0.78,	0.78,
0.12,	0.12,
0.55,	0.55,
2.81,	2.81,
-3.1,	-3.1,
-1.5,	-1.5,
0.33,]	0.33,]
loss 1.25347	loss 1.25353

gradient dW:

[-2.5,
0.6,
?,
?.
(1.25353 - 1.25347)/0.0001
= 0.6

$$\frac{df(x)}{dx} = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$
?,...]

current W:	W + h (third dim):	gradient dW:
[0.34,	[0.34,	[-2.5,
-1.11,	-1.11,	0.6,
0.78,	0.78 + 0.0001 ,	?,
0.12,	0.12,	?,
0.55,	0.55,	?,
2.81,	2.81,	?,
-3.1,	-3.1,	?,
-1.5,	-1.5,	?,
0.33,]	0.33,]	?,]
loss 1.25347	loss 1.25347	19111

current W:	W + h (third dim):
[0.34,	[0.34,
-1.11,	-1.11,
0.78,	0.78 + 0.0001 ,
0.12,	0.12,
0.55,	0.55,
2.81,	2.81,
-3.1,	-3.1,
-1.5,	-1.5,
0.33,]	0.33,]
loss 1.25347	loss 1.25347

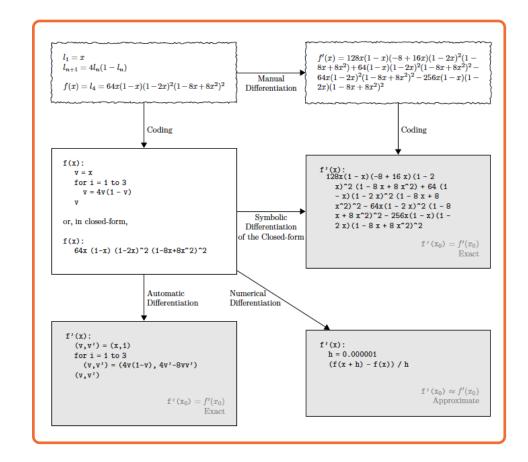
gradient dW: [-2.5, 0.6, (1.25347 - 1.25347)/0.0001 = 0

Several ways to compute $\frac{\partial L}{\partial w_i}$

- Manual differentiation
- Symbolic differentiation
- Numerical differentiation
- Automatic differentiation

More on **autodiff**:

https://www.cs.toronto.edu/~rgrosse/courses/csc421_201 9/readings/L06%20Automatic%20Differentiation.pdf



Numerical vs Analytic Gradients

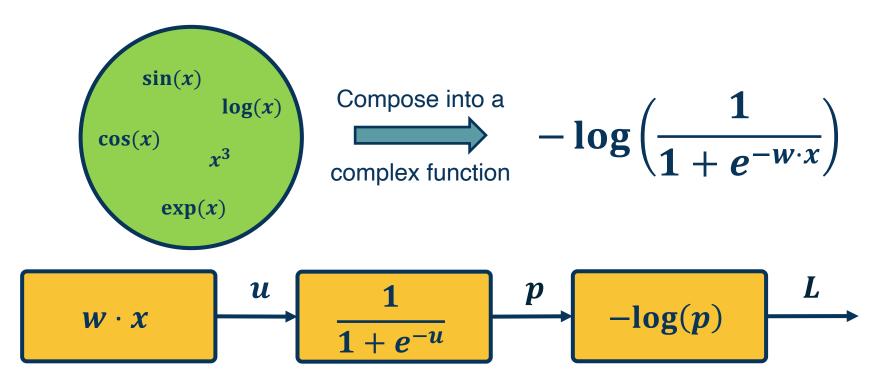
$$rac{df(x)}{dx} = \lim_{h o 0} rac{f(x+h) - f(x)}{h}$$

Numerical gradient: slow :(, approximate :(, easy to write :)
Analytic gradient: fast :), exact :), error-prone :(

Almost all differentiable functions that you can think of have analytical gradients implemented in popular libraries, e.g., PyTorch, TensorFlow.

If you want to derive your own gradients, check your implementation with numerical gradient.
This is called a **gradient check**.

Composing simple functions creates complex analytical gradients



Adapted from slides by: Marc'Aurelio Ranzato, Yann LeCun



$$\frac{\partial L}{\partial w} = \frac{\partial L}{\partial p} \frac{\partial p}{\partial u} \frac{\partial u}{\partial w}$$

Next time: Chain rule and Backpropagation!

Adapted from slides by: Marc'Aurelio Ranzato, Yann LeCun



The gradient descent algorithm

- 1. Choose a model: f(x, W) = Wx
- 2. Choose loss function: $L_i = |y Wx_i|^2$
- 3. Calculate partial derivative for each parameter: $\frac{\partial L}{\partial w_i}$
- 4. Update the parameters: $w_i = w_i \frac{\partial L}{\partial w_i}$
- 5. Add learning rate to prevent too big of a step: $w_i = w_i \alpha \frac{\partial L}{\partial w_i}$
- Repeat 3-5



$$\frac{\partial L}{\partial w} = \frac{\partial L}{\partial p} \frac{\partial p}{\partial u} \frac{\partial u}{\partial w}$$

Next time: Chain rule and Backpropagation!

Linear **Algebra** View: **Vector** and **Matrix Sizes**



Conventions:

- Size of derivatives for scalars, vectors, and matrices: Assume we have scalar $s \in \mathbb{R}^1$, vector $v \in \mathbb{R}^m$, i.e. $v = [v_1, v_2, ..., v_m]^T$ and matrix $M \in \mathbb{R}^{k \times \ell}$
- What is the size of $\frac{\partial v}{\partial s}$? $\mathbb{R}^{m \times 1}$ (column vector of size m)

 What is the size of $\frac{\partial s}{\partial v}$? $\mathbb{R}^{1 \times m}$ (row vector of size m) $\frac{\partial v_1}{\partial s} = \frac{\partial v_2}{\partial s}$ \vdots $\frac{\partial v_m}{\partial s} = \frac{\partial v_1}{\partial s}$
- lacktriangle What is the size of $rac{\partial s}{\partial v}$? $\mathbb{R}^{1 imes m}$ (row vector of size m)

$$\left[\frac{\partial s}{\partial v_1} \frac{\partial s}{\partial v_1} \cdots \frac{\partial s}{\partial v_m}\right]$$

Conventions:

• What is the size of $\frac{\partial v^1}{\partial v^2}$? A matrix:

Row i

This matrix of partial derivatives is called a Jacobian

(Note this is slightly different convention than on Wikipedia)



Conventions:

What is the size of $\frac{\partial s}{\partial M}$? A matrix:

$$\begin{bmatrix} \frac{\partial s}{\partial m_{[1,1]}} & \dots & \dots & \dots & \dots \\ \frac{\partial s}{\partial m_{[i,j]}} & \dots & \frac{\partial s}{\partial m_{[i,j]}} & \dots & \dots \end{bmatrix}$$

- What is the size of $\frac{\partial L}{\partial W}$?
 - Remember that loss is a scalar and W is a matrix:

$$\begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1m} & b1 \\ w_{21} & w_{22} & \cdots & w_{2m} & b2 \\ w_{31} & w_{32} & \cdots & w_{3m} & b3 \end{bmatrix}$$

Jacobian is also a matrix:

$$\begin{bmatrix} \frac{\partial L}{\partial w_{11}} & \frac{\partial L}{\partial w_{12}} & \cdots & \frac{\partial L}{\partial w_{1m}} & \frac{\partial L}{\partial b_1} \\ \frac{\partial L}{\partial w_{21}} & \cdots & \cdots & \frac{\partial L}{\partial w_{2m}} & \frac{\partial L}{\partial b_2} \\ \cdots & \cdots & \cdots & \frac{\partial L}{\partial w_{3m}} & \frac{\partial L}{\partial b_3} \end{bmatrix}$$

Batches of data are **matrices** or **tensors** (multi-dimensional matrices)

Examples:

- Each instance is a vector of size m, our batch is of size $[B \times m]$
- Each instance is a matrix (e.g. grayscale image) of size $W \times H$, our batch is $[B \times W \times H]$
- Each instance is a multi-channel matrix (e.g. color image with R,B,G channels) of size C×W×H, our batch is [B×C×W×H]

Jacobians become tensors which is complicated

- Instead, flatten input to a vector and get a vector of derivatives!
- This can also be done for partial derivatives between two vectors, two matrices, or two tensors

