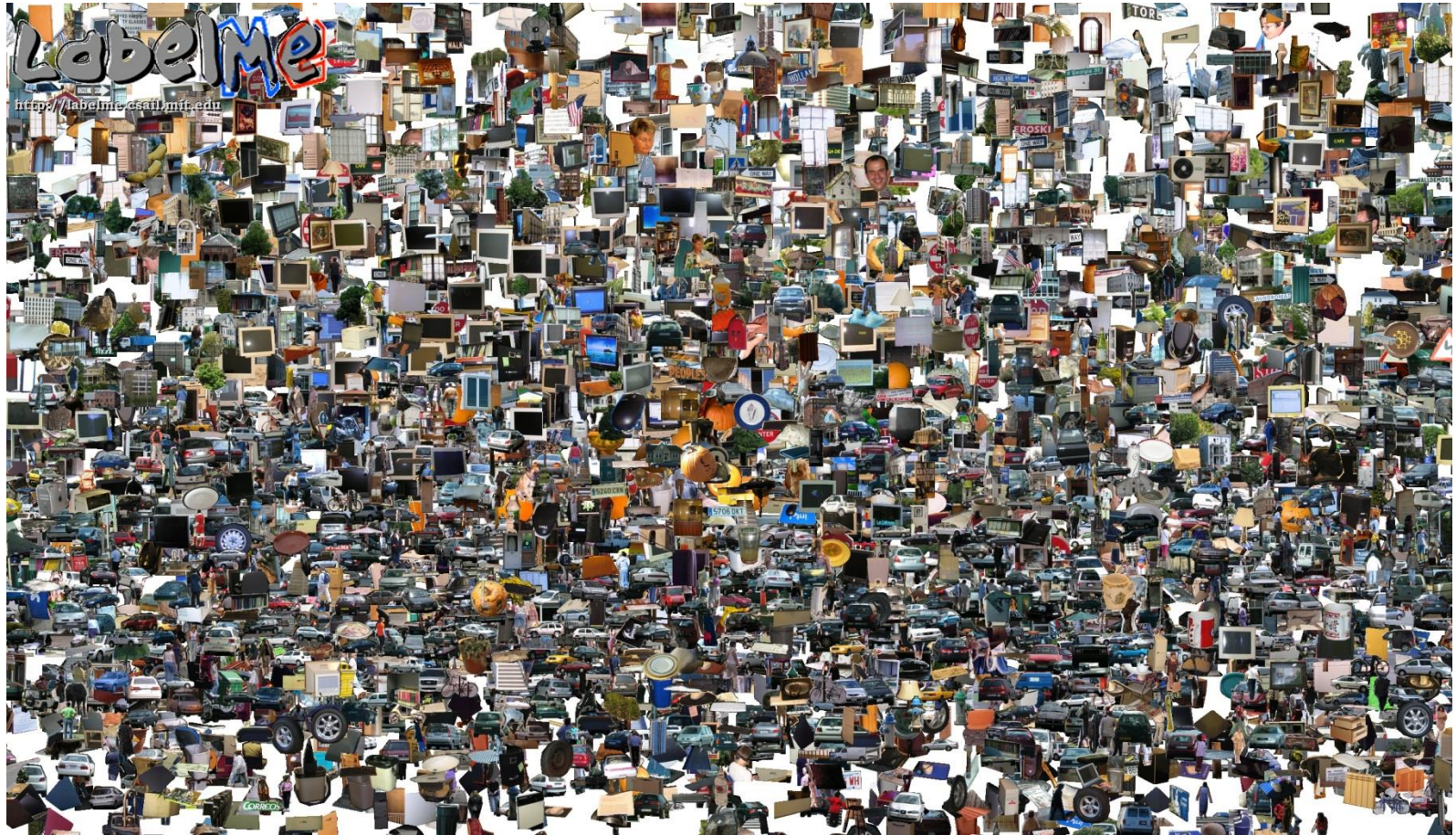


# Opportunities of Scale, Part 2



Computer Vision

James Hays

# Recap

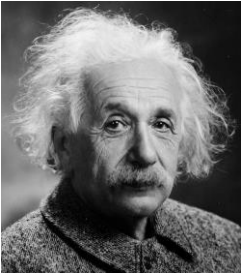
## Opportunities of Scale: Data-driven methods

- Previous Lecture
  - The unreasonable effectiveness of data
  - Scene completion
- Today
  - Im2gps
  - Recognition via Tiny Images
- Project 5 Intro

# The Unreasonable Effectiveness of Math



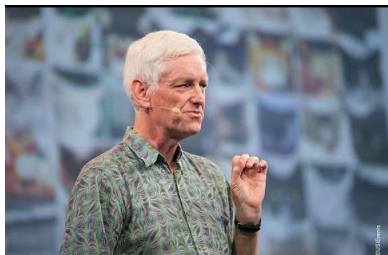
- “The miracle of the appropriateness of the language of mathematics...” **Eugene Wigner**



- “The most incomprehensible thing about the universe is that it is comprehensible.” **Albert Einstein**
- “There is only one thing which is more unreasonable than the unreasonable effectiveness of mathematics in physics, and this is the unreasonable ineffectiveness of mathematics in biology.” **Israel Gelfand**

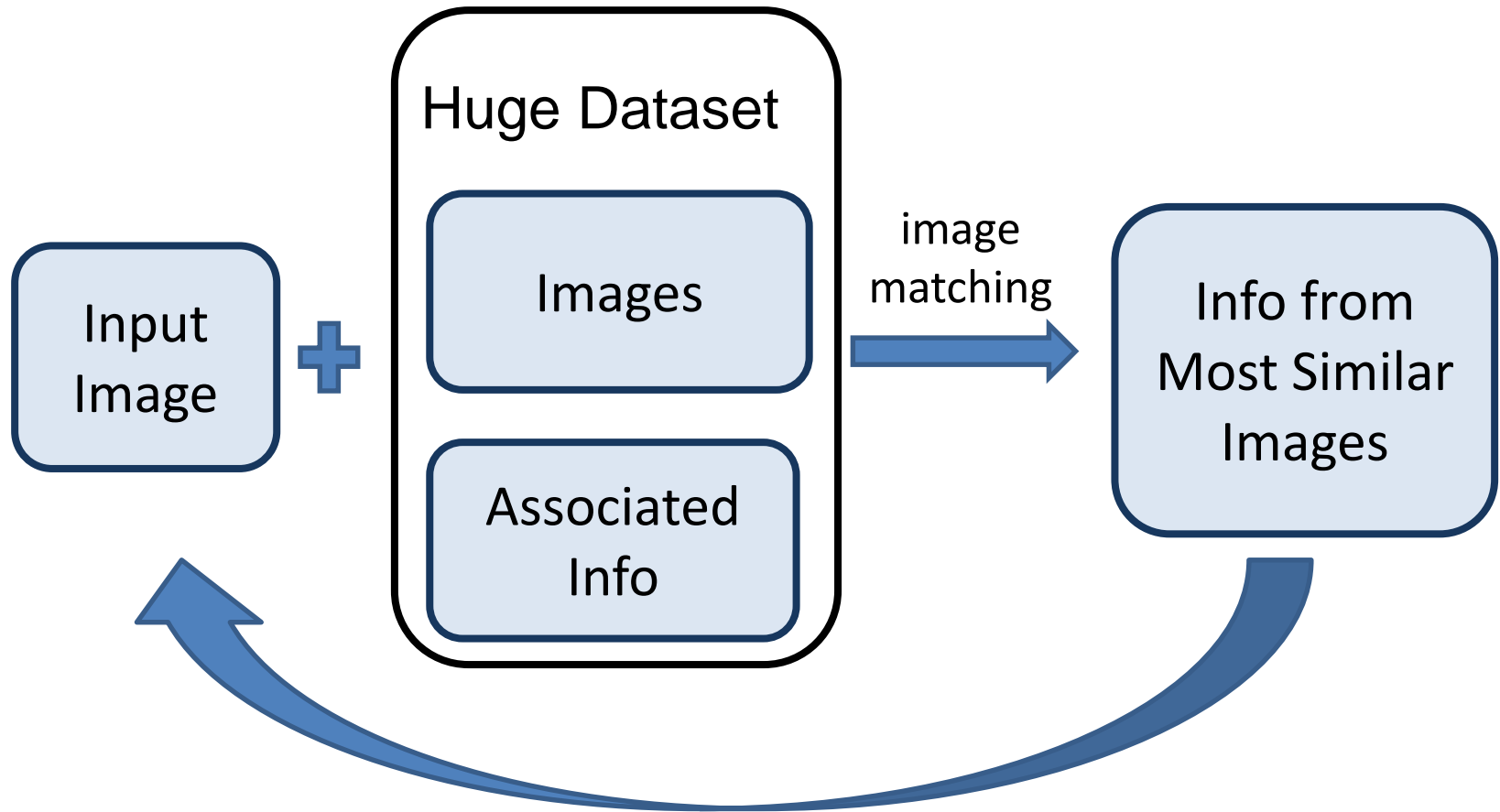


- “We should stop acting as if our goal is to author extremely elegant theories, and instead embrace complexity and make use of the best ally we have: the unreasonable effectiveness of data.” **Peter Norvig**

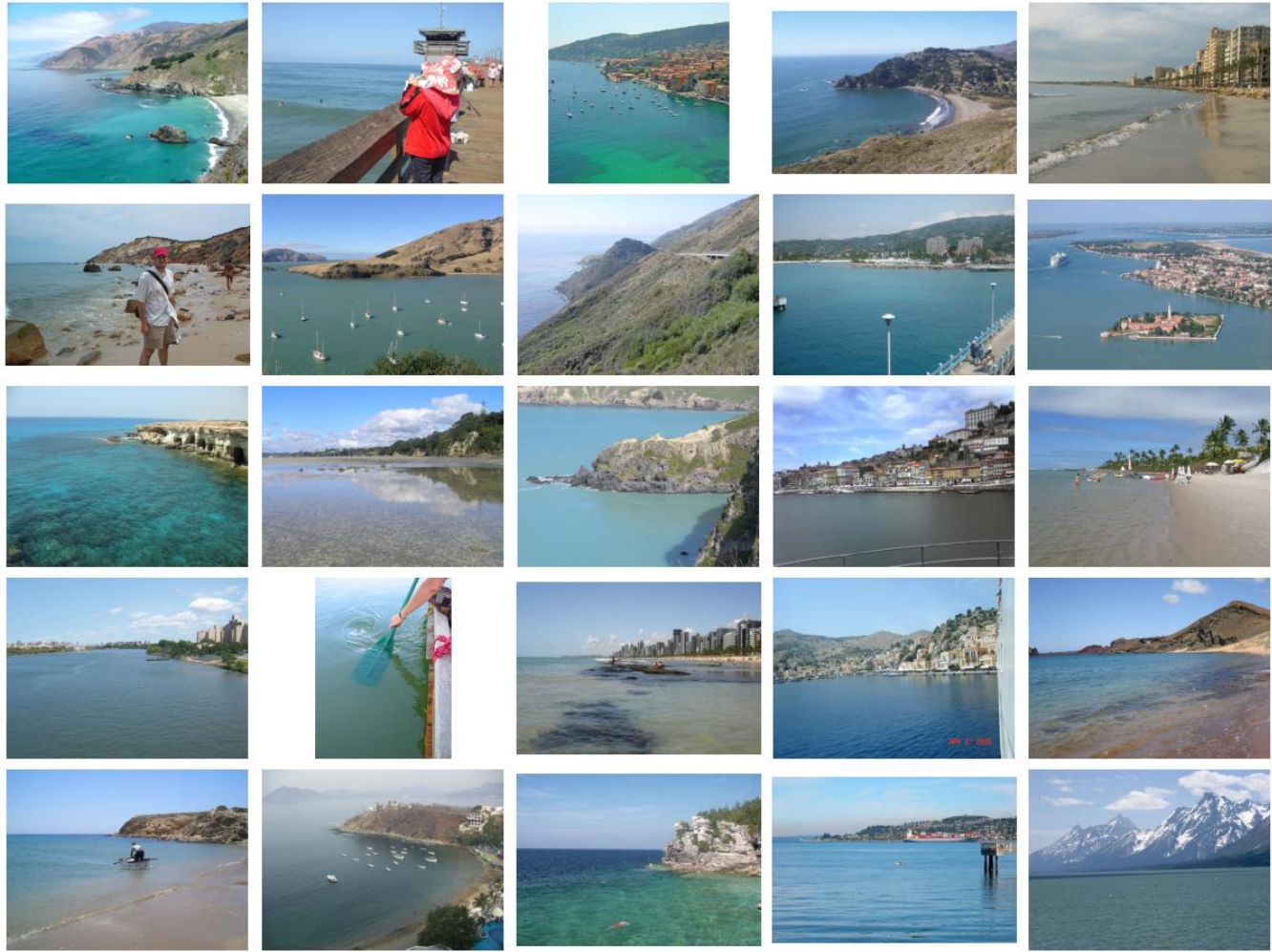
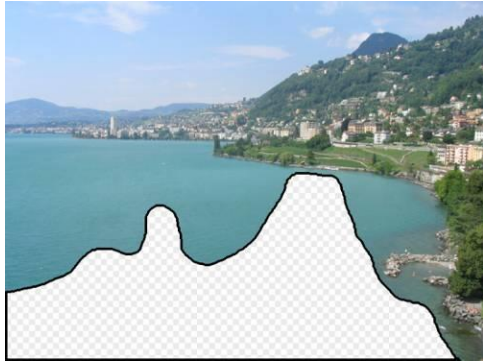




# General Principal



Hopefully, If you have enough images, the dataset will contain very similar images that you can find with simple matching methods.



... 200 total





Graph cut + Poisson blending

# im2gps (Hays & Efros, CVPR 2008)



6 million geo-tagged Flickr images

<http://graphics.cs.cmu.edu/projects/im2gps/>



How much can an image tell about its geographic location?







Paris



Paris



Paris



Paris



Paris



Paris



Paris



Madrid



Rome



Paris



Cuba



Paris



Paris



Poland



Paris



Paris

Nearest Neighbors according to gist + bag of SIFT + color histogram + a few others





Im2gps





# Example Scene Matches



Madrid



england



France



Paris



Croatia



heidelberg



Macau



Malta



Cairo



Italy



Italy



Italy



Latvia



europe

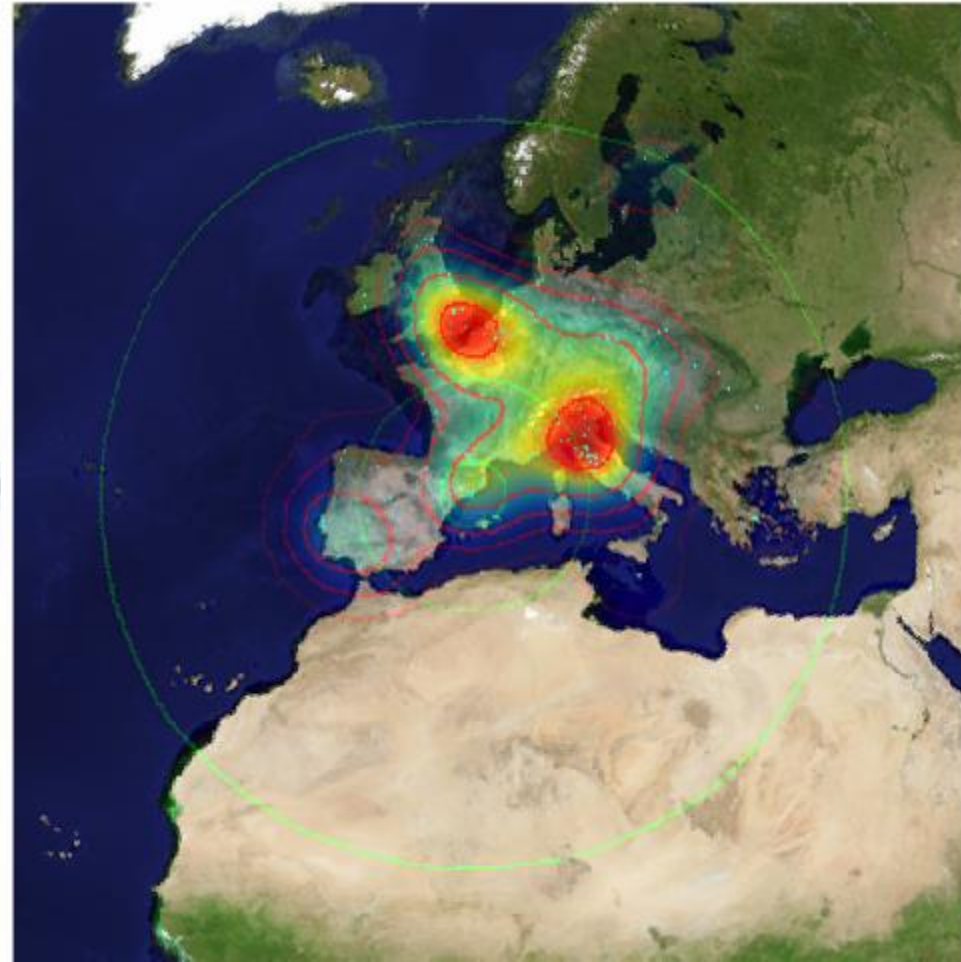
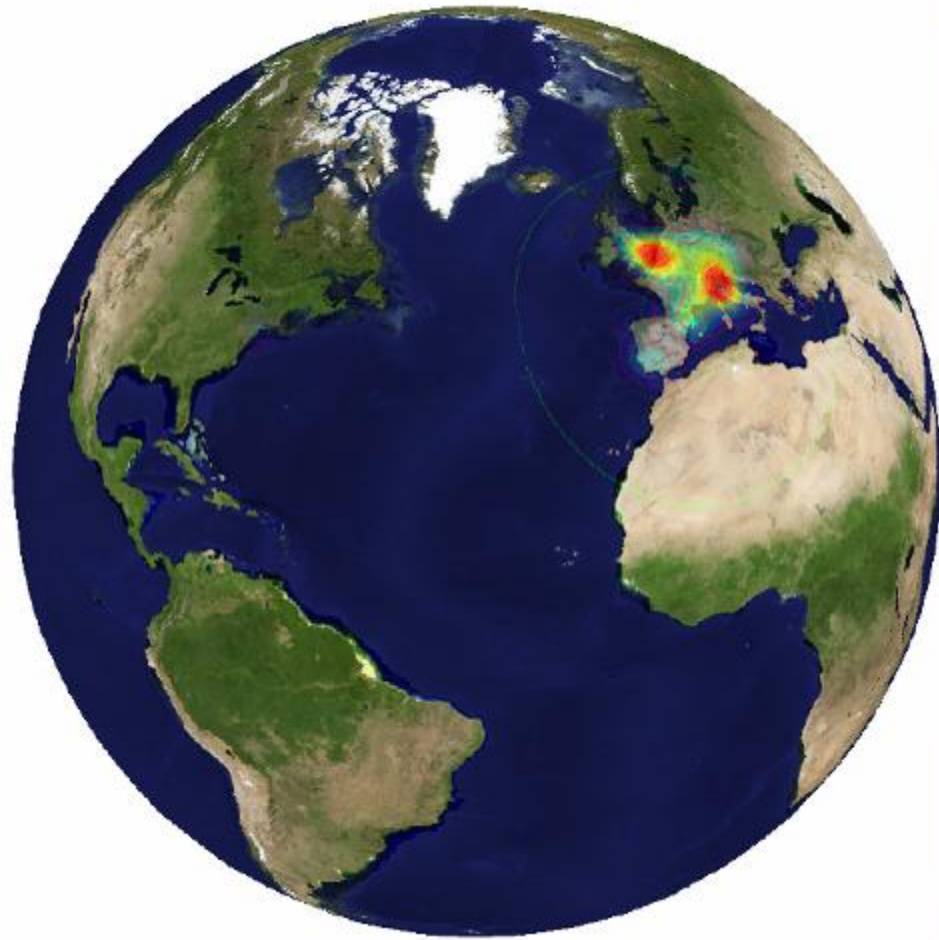


Barcelona



Austria

# Voting Scheme





im2gps







Philippines



Houston



Thailand



Houston



Maldives



Philippines



NewZealand



Bermuda



Palau



Mexico2



Brazil



Mendoza



Brazil



Thailand



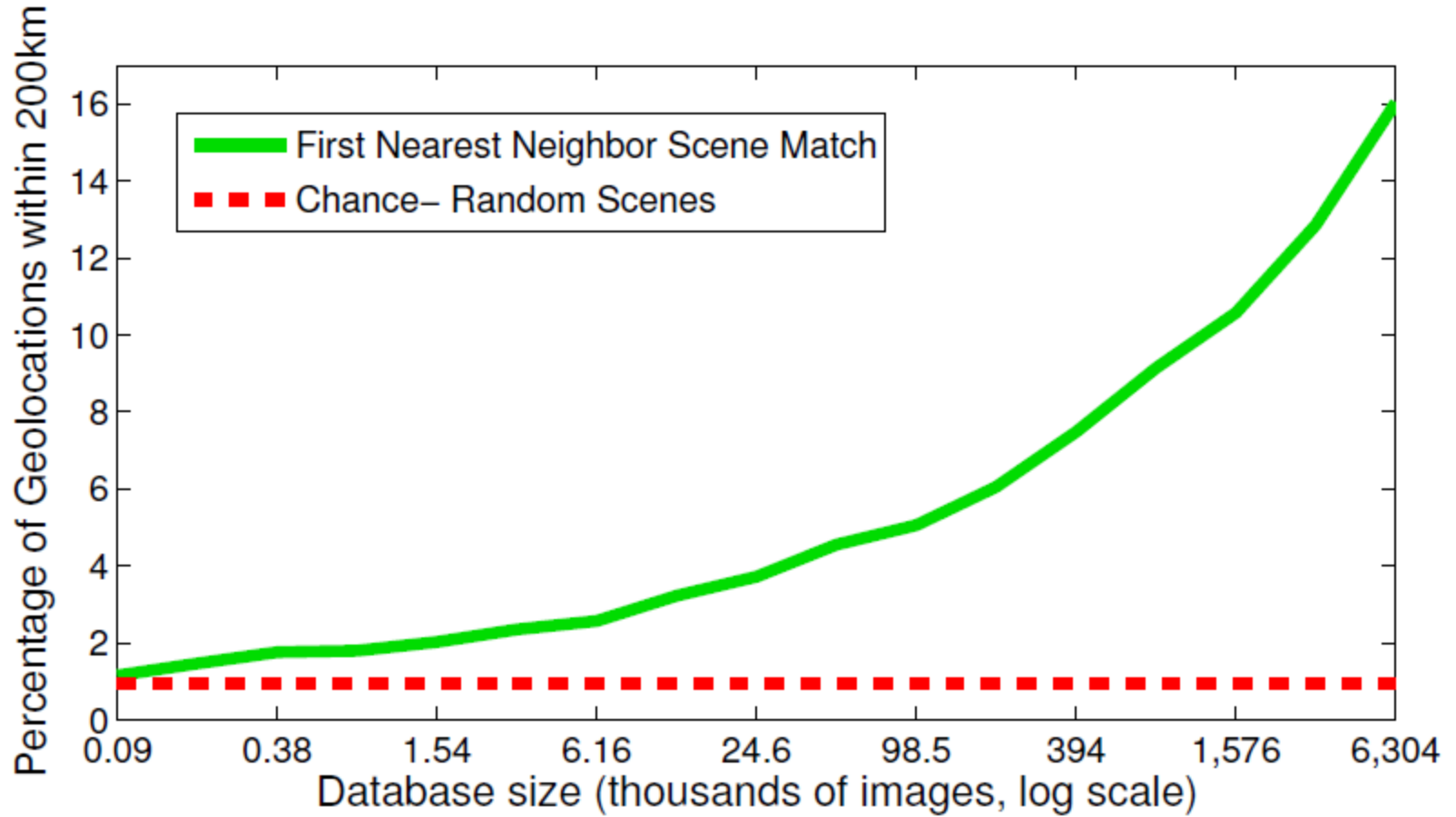
Arkansas



Hawaii



# Effect of Dataset Size





# Population density ranking

## High Predicted Density



## Low Predicted Density

# Where is This?



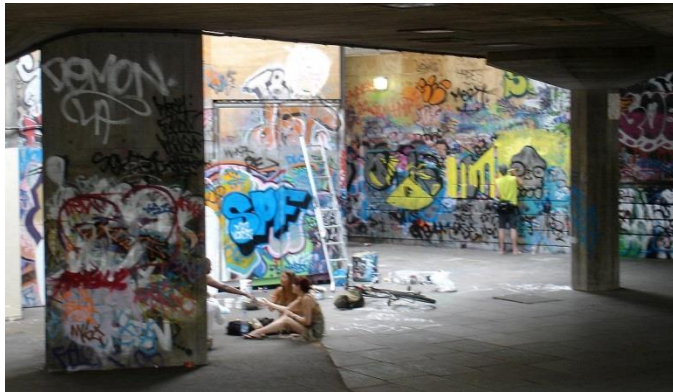
[Olga Vesselova, Vangelis Kalogerakis, Aaron Hertzmann, James Hays, Alexei A. Efros. Image Sequence Geolocation. ICCV'09]

Where is This?





# Where are These?



15:14,  
June 18<sup>th</sup>, 2006



16:31,  
June 18<sup>th</sup>, 2006

# Where are These?



15:14,  
June 18<sup>th</sup>, 2006



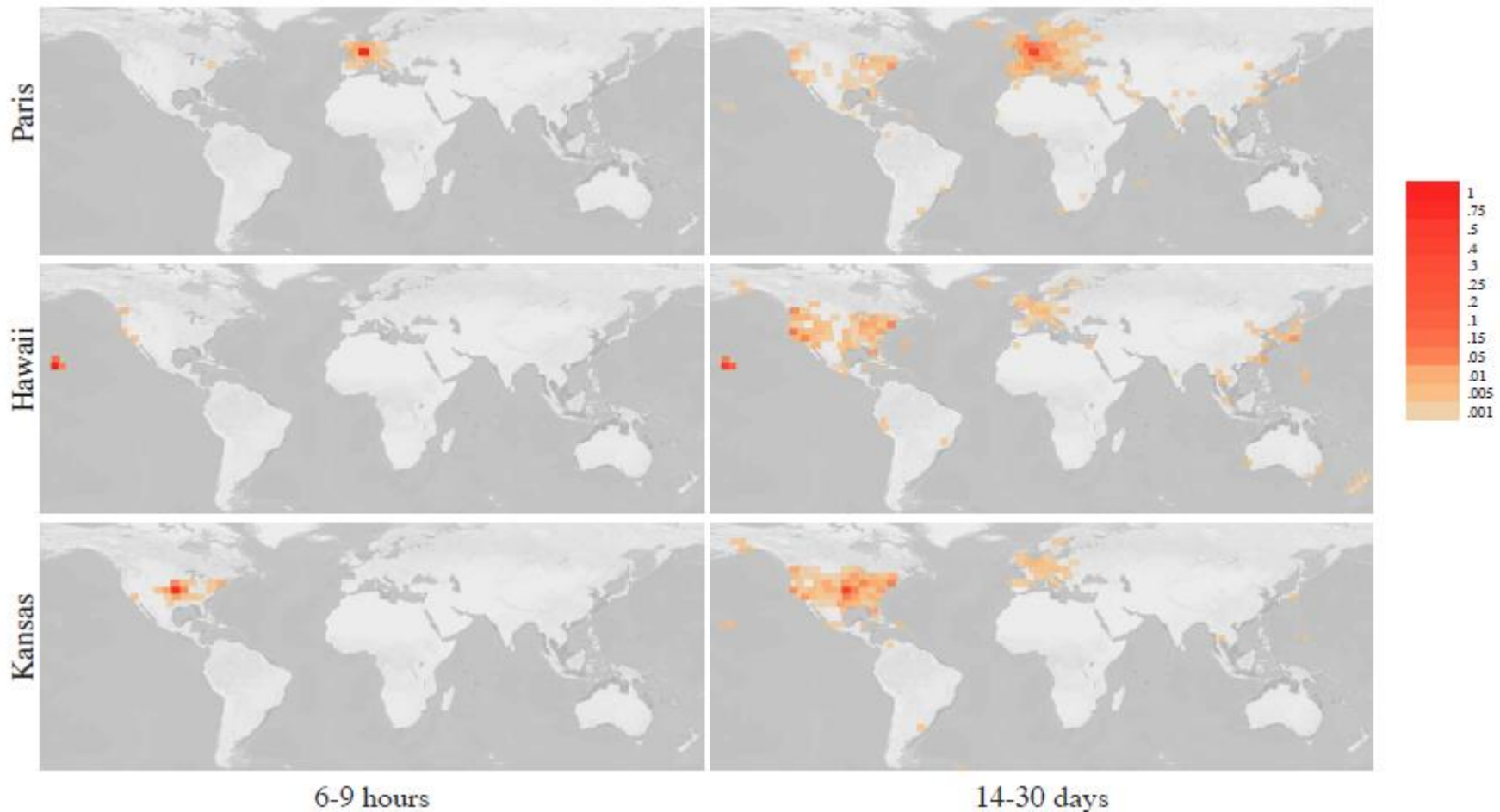
16:31,  
June 18<sup>th</sup>, 2006



17:24,  
June 19<sup>th</sup>, 2006

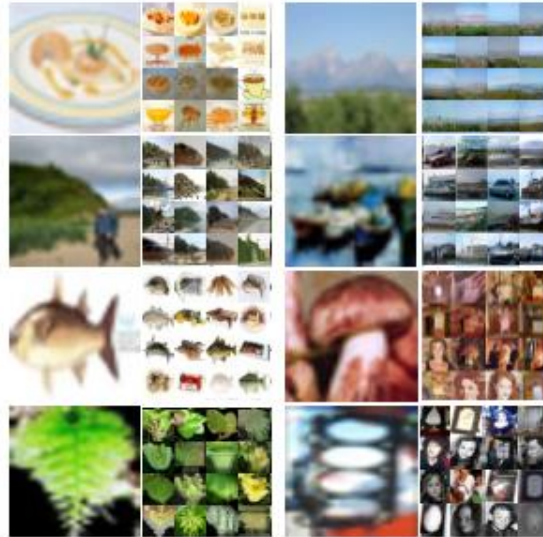
# Results

- im2gps – 10% (geo-loc within 400 km)
- temporal im2gps – 56%





# Tiny Images



80 million tiny images: a large dataset for non-parametric object and scene recognition  
Antonio Torralba, Rob Fergus and William T. Freeman. PAMI 2008.

<http://groups.csail.mit.edu/vision/TinyImages/>

256x256



256x256



32x32

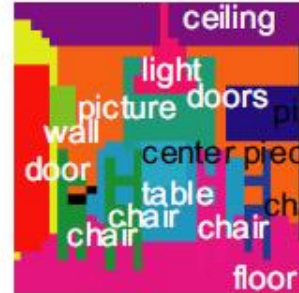
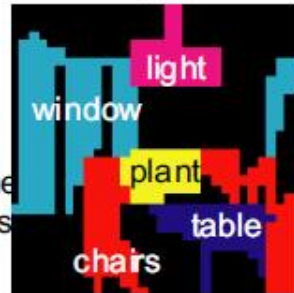
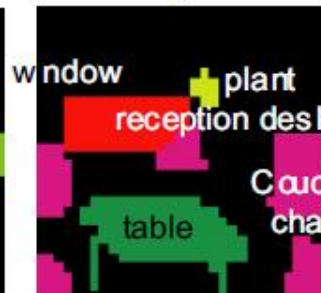
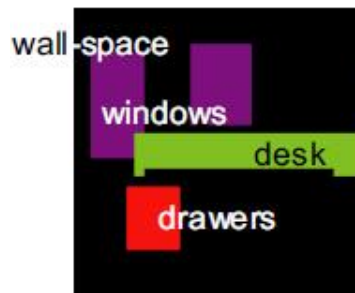


office

waiting area

dining room

dining room

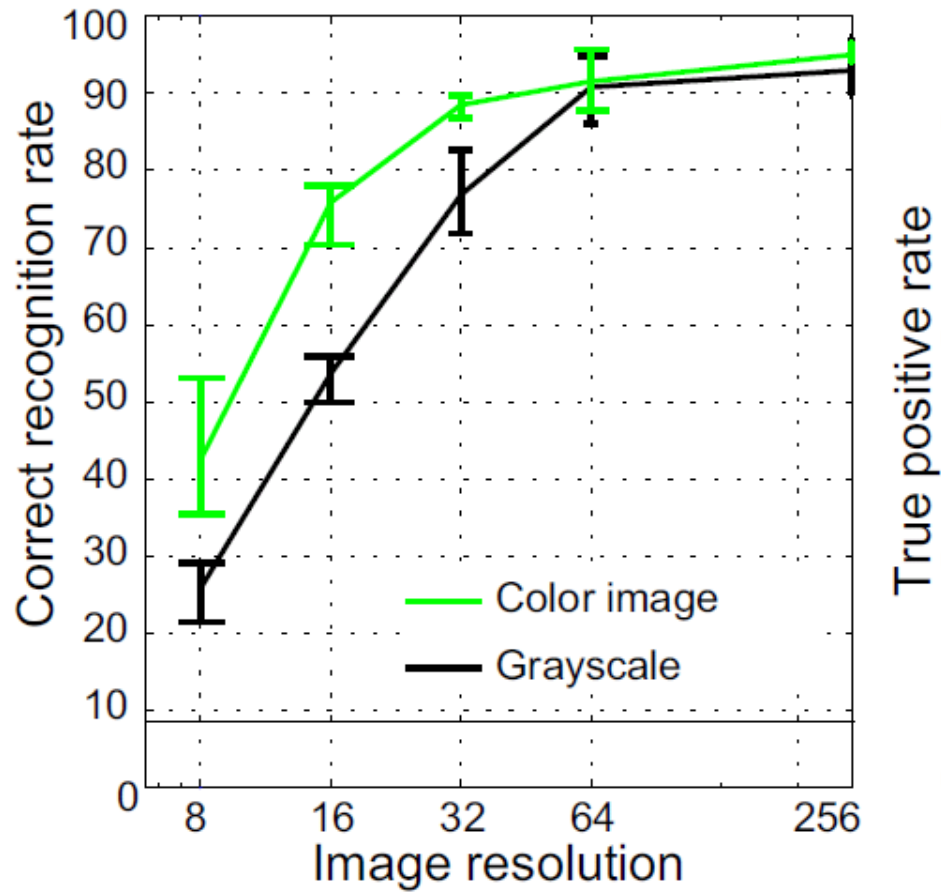


### c) Segmentation of 32x32 images





# Human Scene Recognition

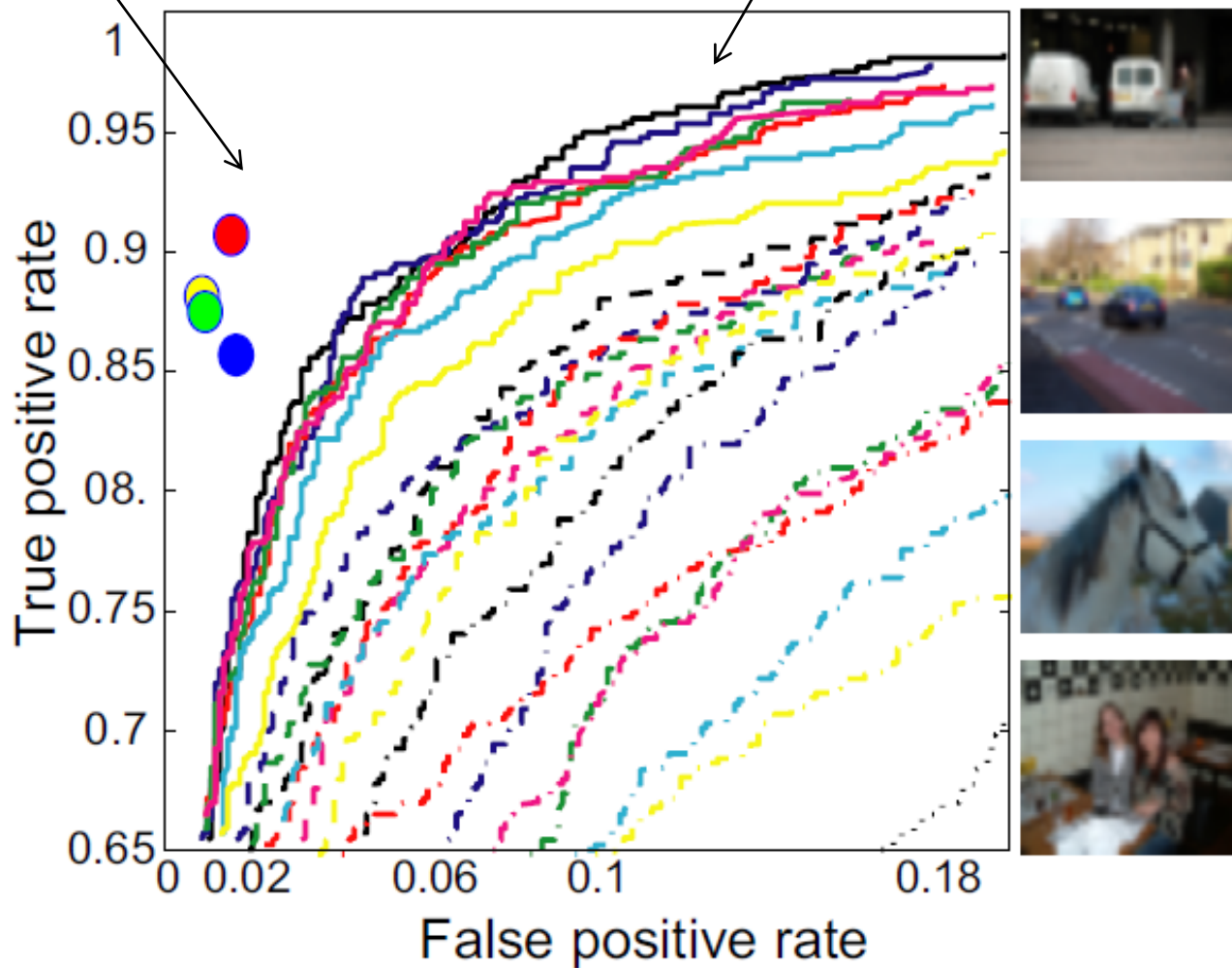


a) Scene recognition

# Humans vs. Computers: Car-Image Classification

Humans for 32 pixel tall images

Various computer vision algorithms for full resolution images



# Powers of 10

Number of images on my hard drive:

$10^4$



Number of images seen during my first 10 years:

(3 images/second \* 60 \* 60 \* 16 \* 365 \* 10 = 630720000)

$10^8$



Number of images seen by all humanity:

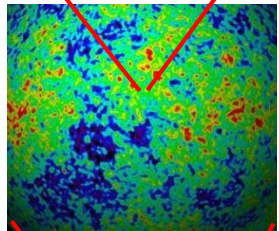
$106,456,367,669 \text{ humans}^1 * 60 \text{ years} * 3 \text{ images/second} * 60 * 60 * 16 * 365 =$   
1 from <http://www.prb.org/Articles/2002/HowManyPeopleHaveEverLivedonEarth.aspx>

$10^{20}$



Number of photons in the universe:

$10^{88}$



Number of all 32x32 images:

$256^{32*32*3} \sim 10^{7373}$

$10^{7373}$





# Scenes are unique





# But not all scenes are so original



# Lots Of Images

Target

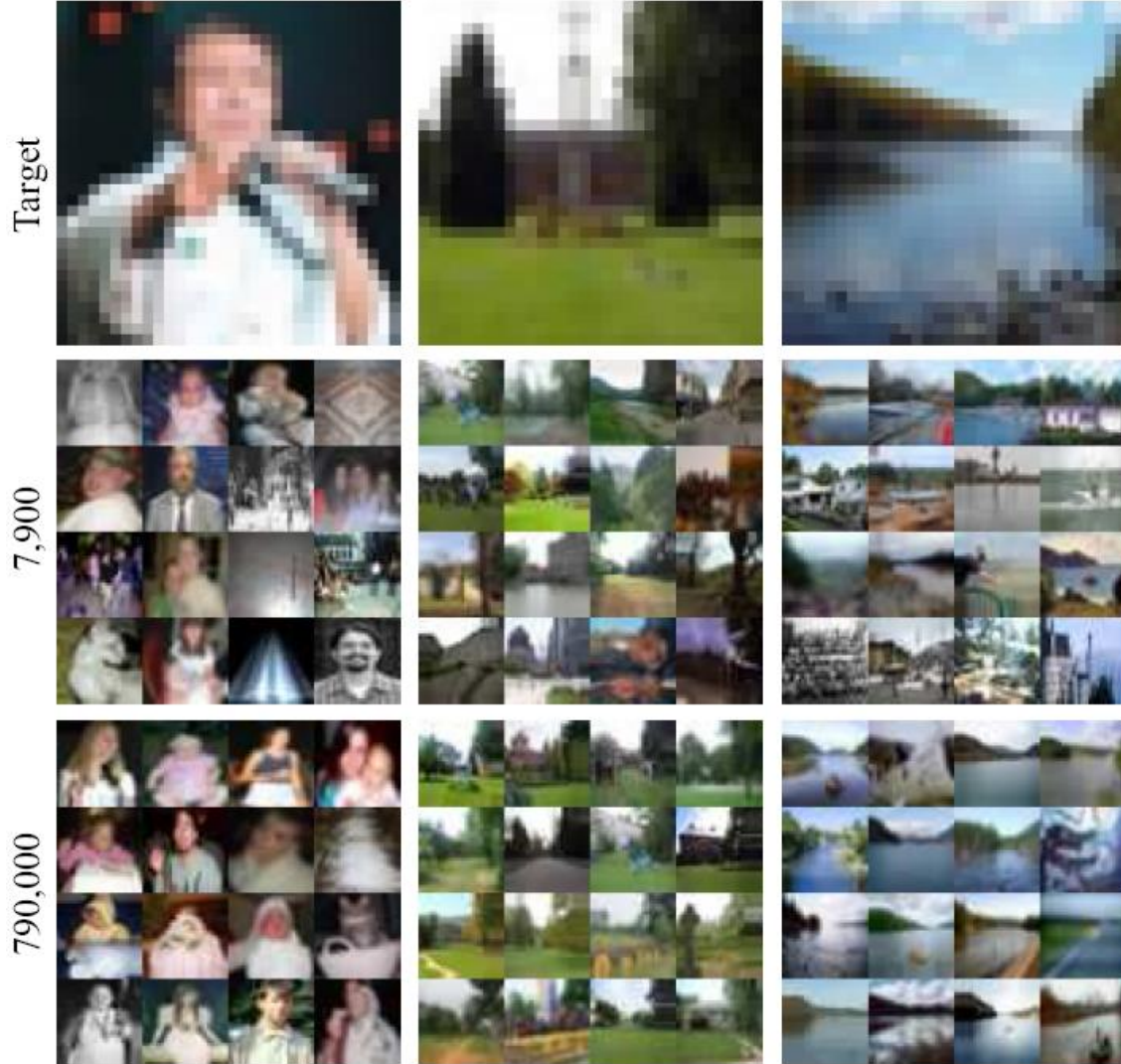


7,900





# Lots Of Images



# Lots Of Images

Target



7,900



790,000



79,000,000



# Application: Automatic Colorization



Input



Color Transfer



Color Transfer



Matches (gray)



Matches (w/ color)



Avg Color of Match



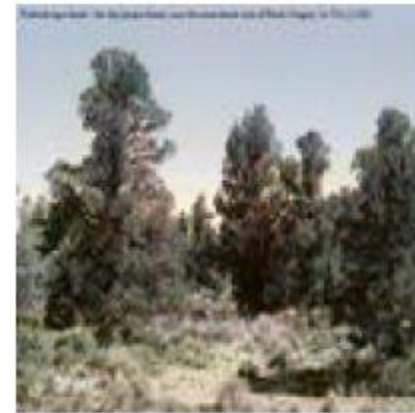
# Application: Automatic Colorization



Input



Color Transfer



Color Transfer



Matches (gray)



Matches (w/ color)



Avg Color of Match

# Automatic Orientation Examples

0.70



0.64



0.66



0.64



0.86



0.76



0.79



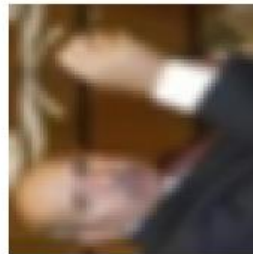
0.77



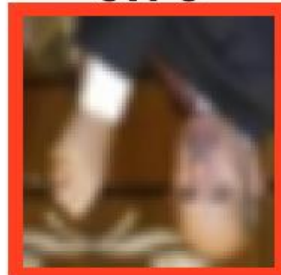
0.66



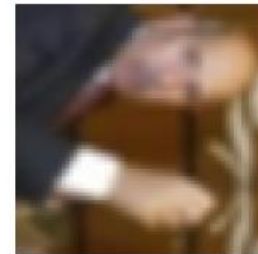
0.62



0.70



0.63



# Summary

- With billions of images on the web, it's often possible to find a close nearest neighbor
- In such cases, we can shortcut hard problems by “looking up” the answer, stealing the labels from our nearest neighbor
- For example, simple (or learned) associations can be used to synthesize background regions, colorize, or recognize objects





# Project 5

- <http://www.cc.gatech.edu/~hays/compvision/proj5/>

