Encoding Intelligent Agents for Uncertain, Unknown, and Dynamic Tasks: From Programming to Interactive Artificial Learning

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Research Problem

Goal:

End-users can "program" their own machines to do "intelligent" things

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End-users can "program" their own machines to do "intelligent" things

- Challenges
 - System designers have limited a priori knowledge
 - End-users may not be technology experts

Methods

- I. Traditional AI Programming
- 2. Classical Artificial Learning
- 3. Interactive Artificial Learning (IAL)

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Return on User Investment

Agent Competence

User Input

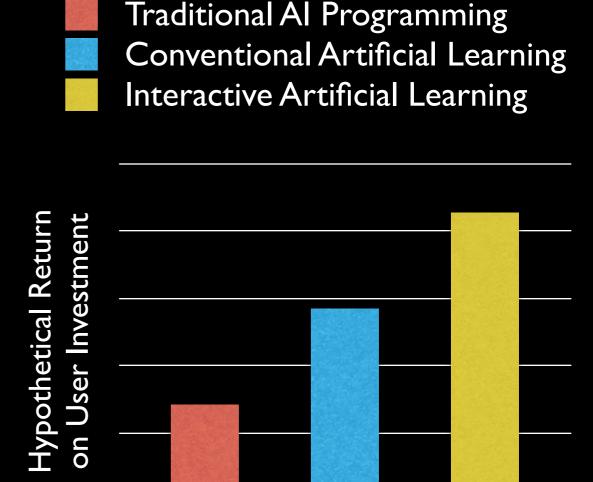
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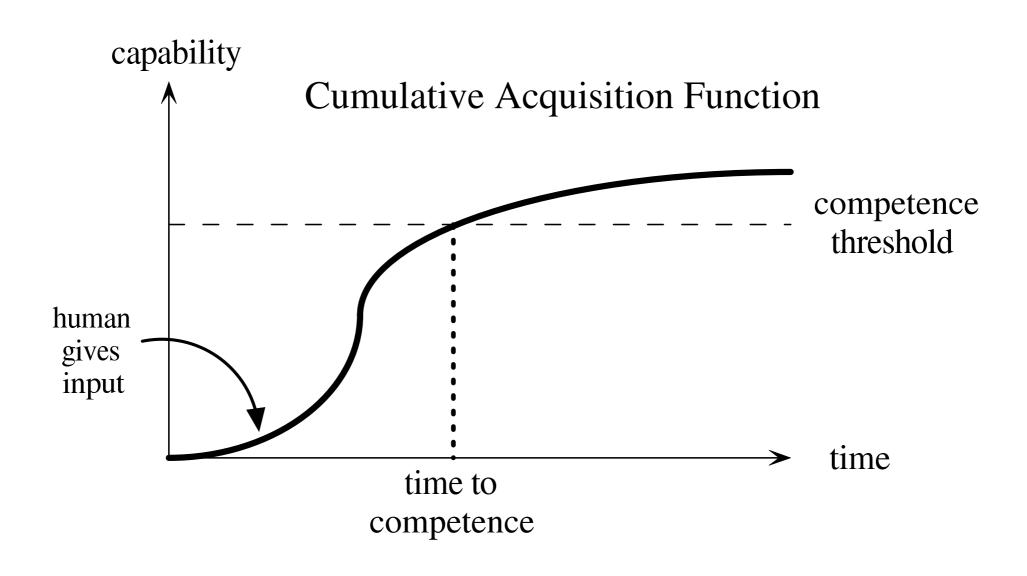
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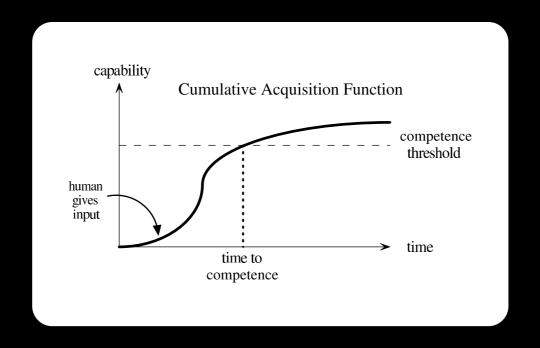


Metrics for IAL

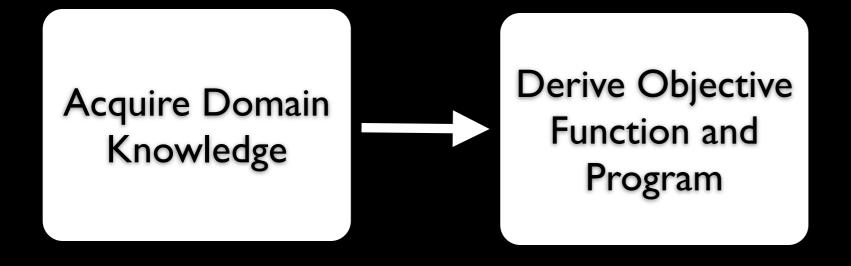


3 Questions for IAL

- What roles should humans play and when do they get involved?
- How should systems be designed to support these human-machine interactions?
- What learning algorithms are most appropriate?



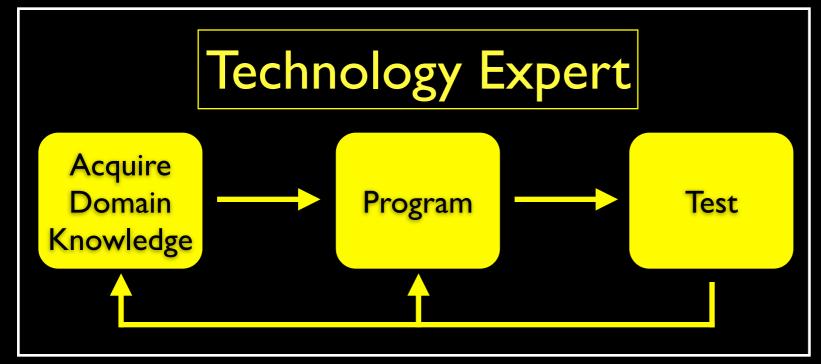
Acquire Domain Knowledge

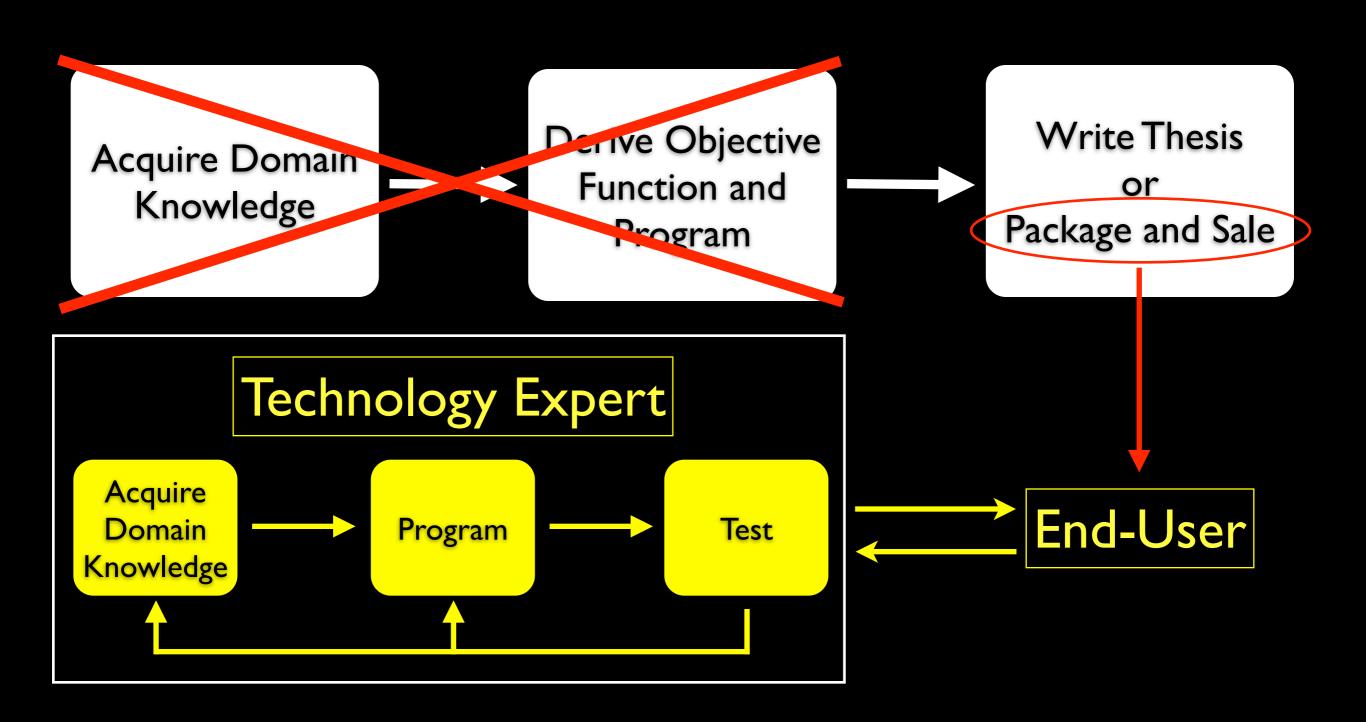




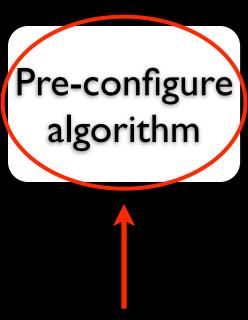




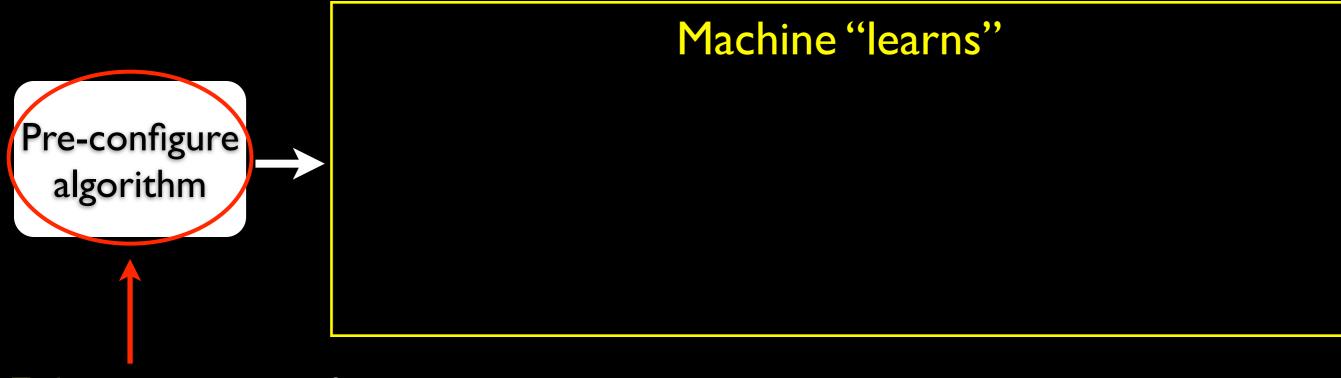




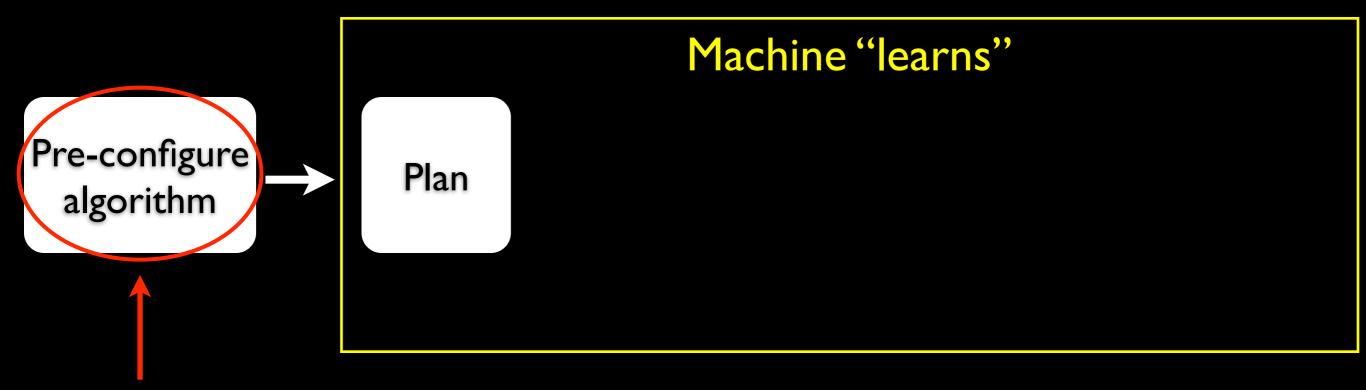
Pre-configure algorithm



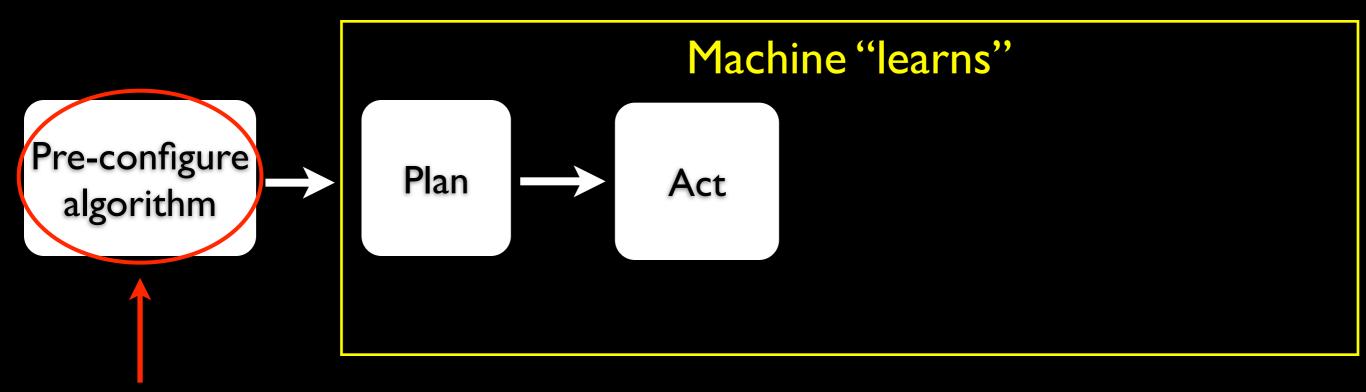
- States and Features
- Reward representation
- Learning representations
- Parameter values
- Etc.



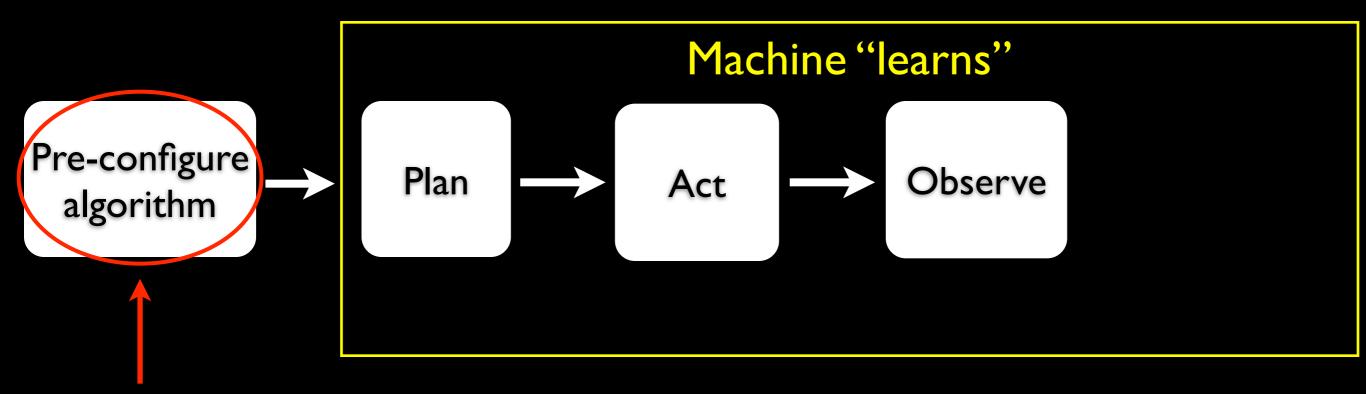
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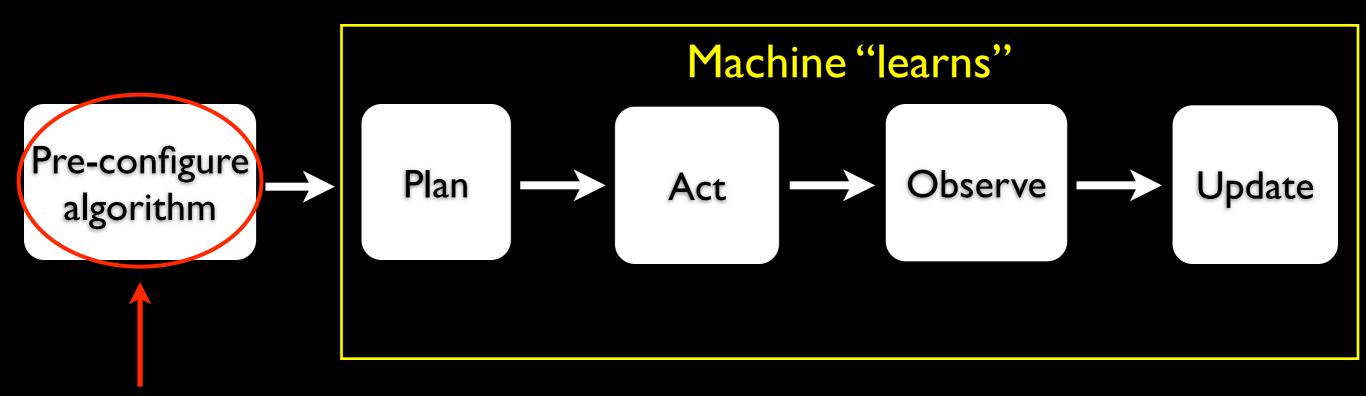
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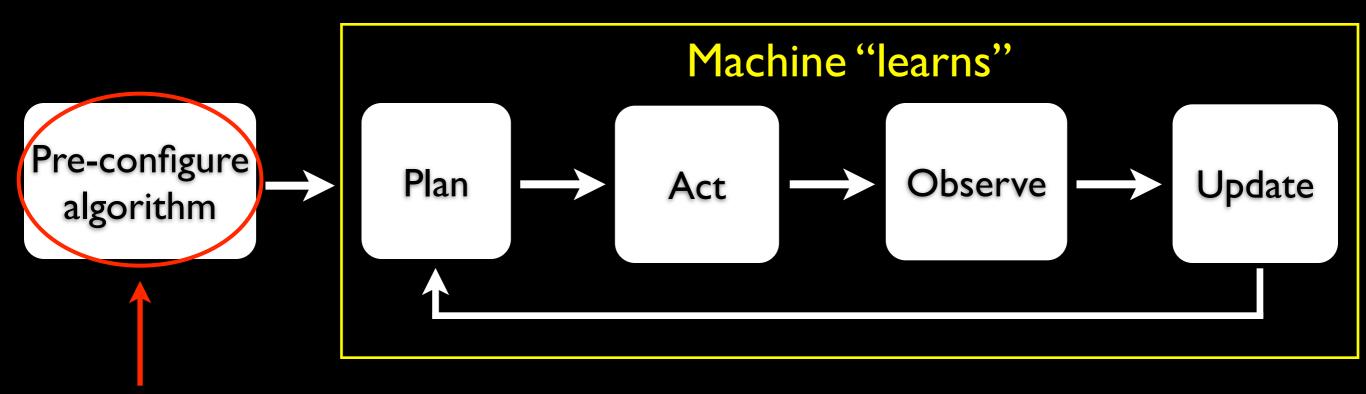
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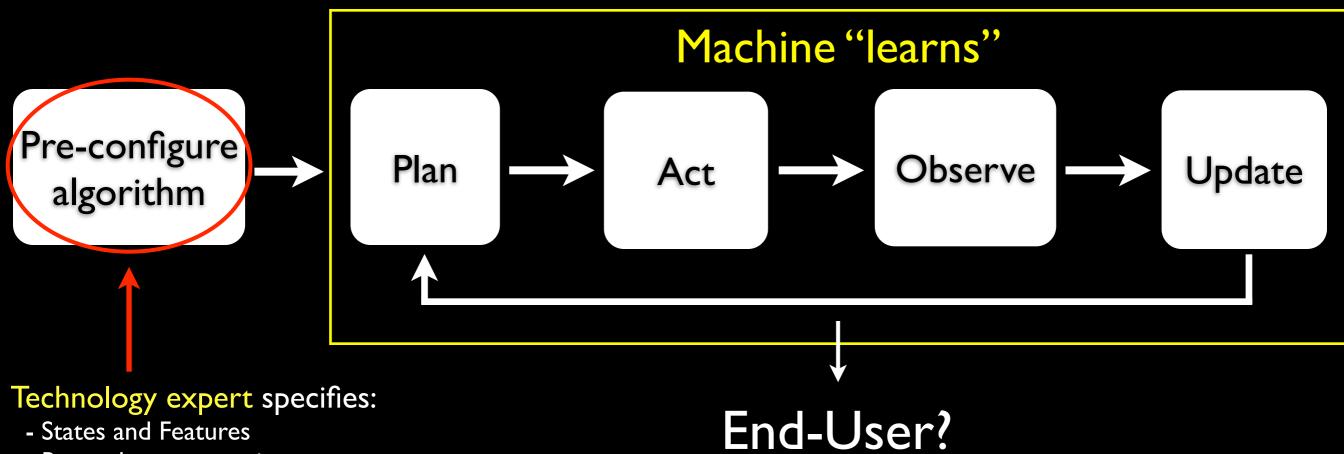
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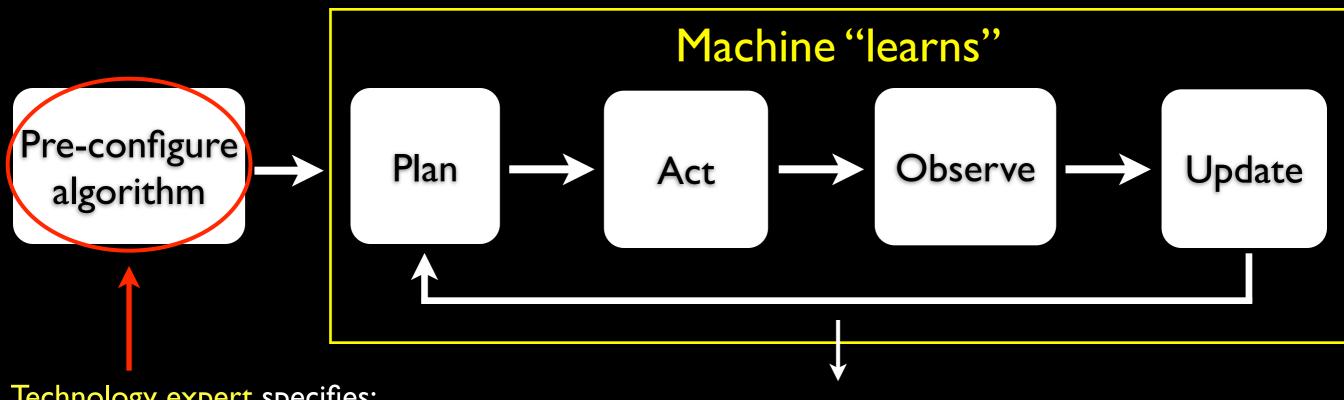
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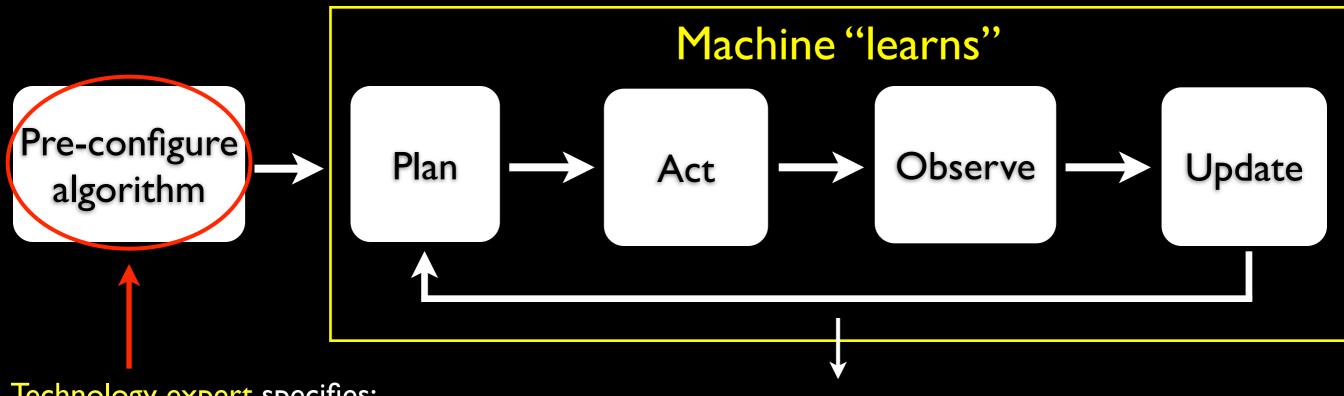


Technology expert specifies:

- States and Features
- Reward representation
- Learning representations
- Parameter values
- Etc.

- Learning process is too slow and dangerous

End-User?

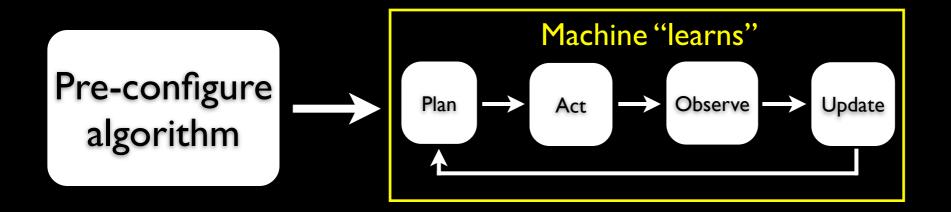


- States and Features
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- End-User?
- Learning process is too slow and dangerous
- Plus

What really happens

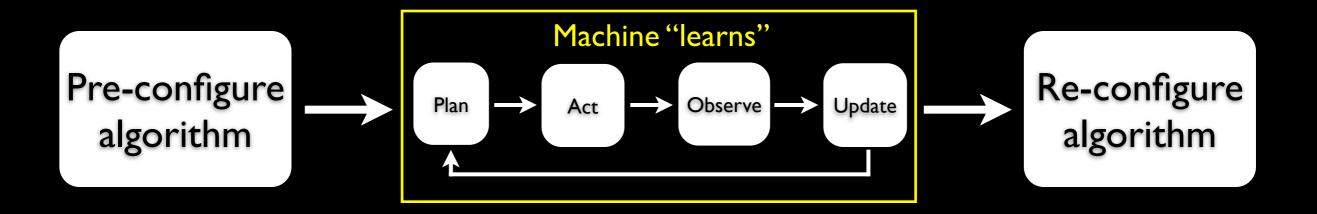
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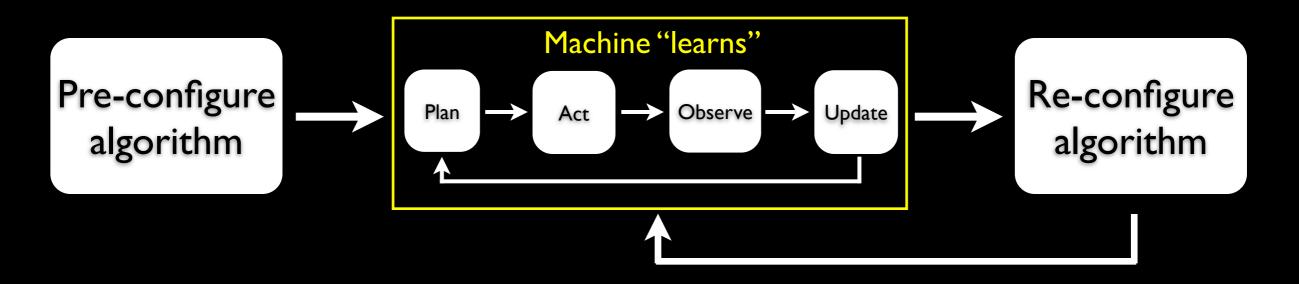
Technology Expert



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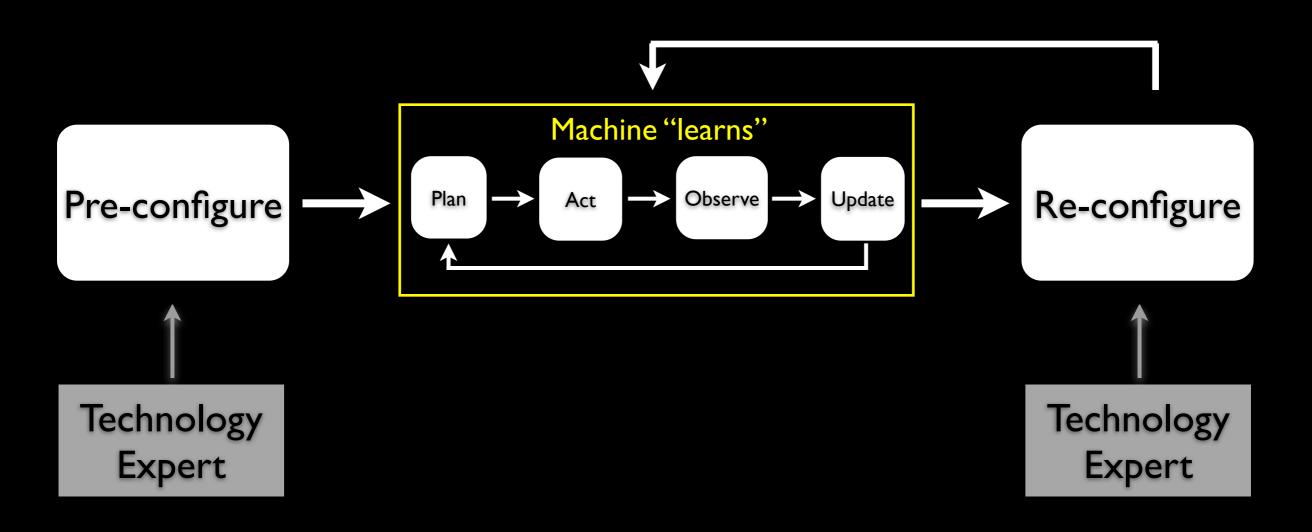
Technology Expert

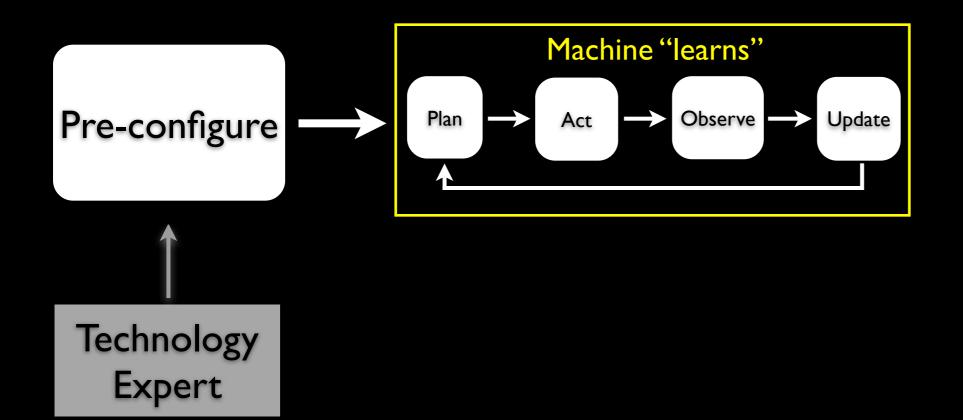


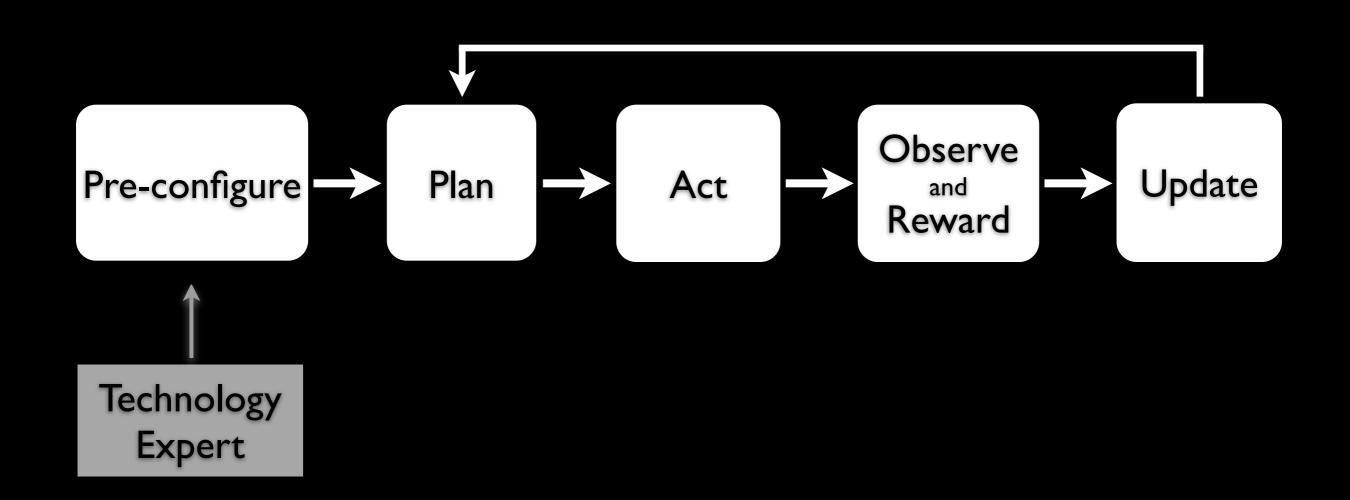
Insane Researcher Skills

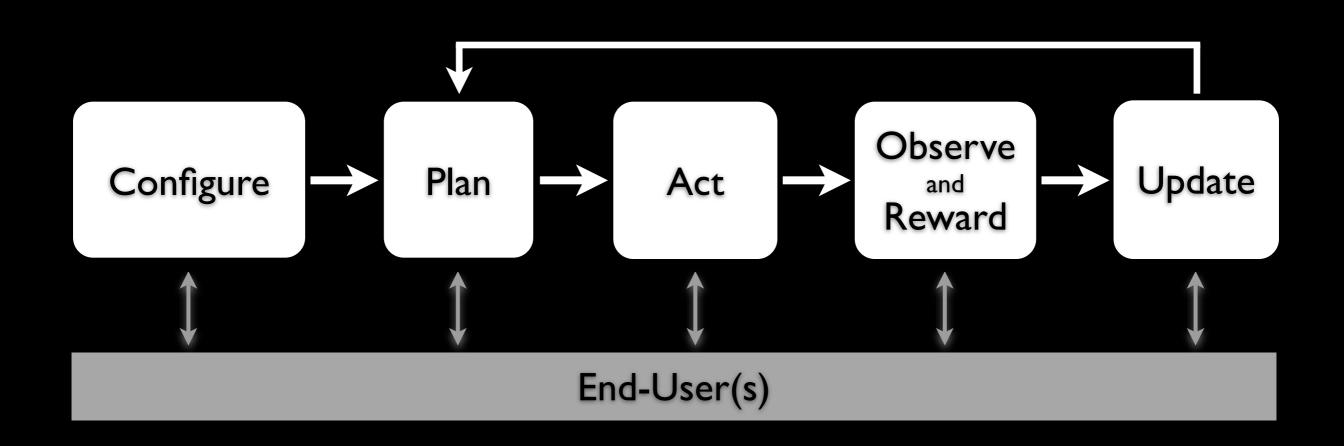


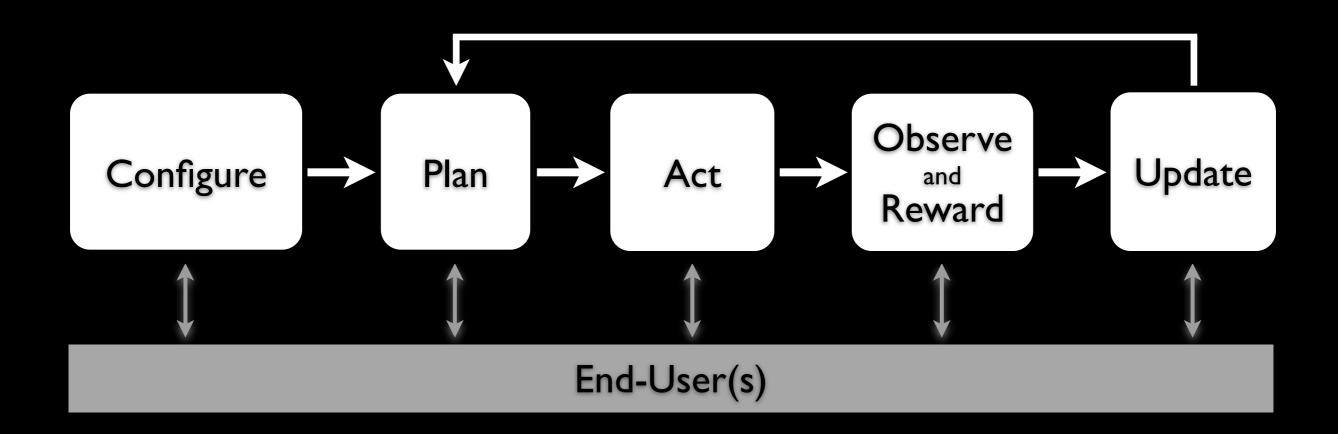








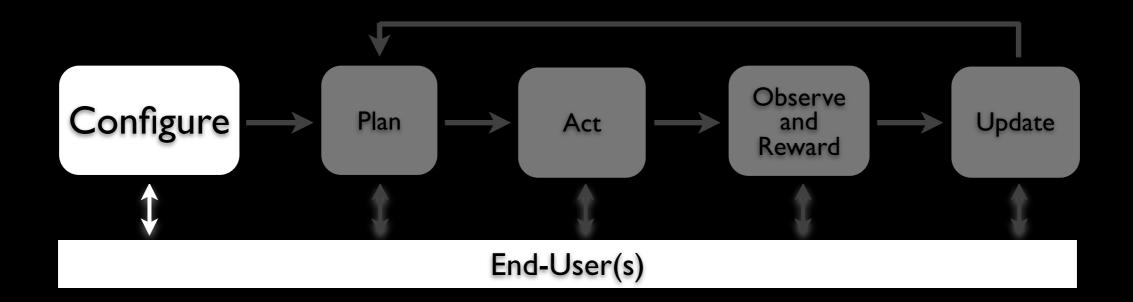




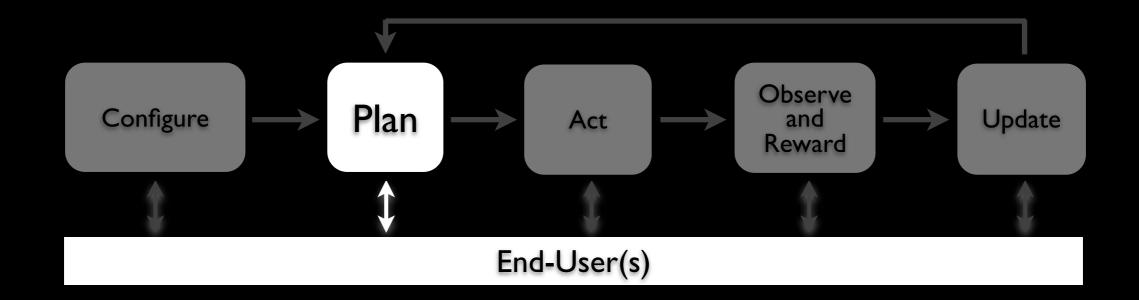
Which interactions are most productive?

What should the interactions be like?

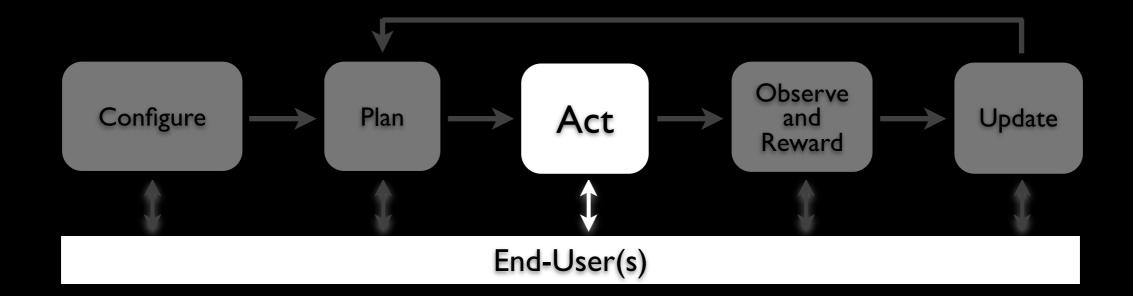
What learning algorithms facilitate these interactions?



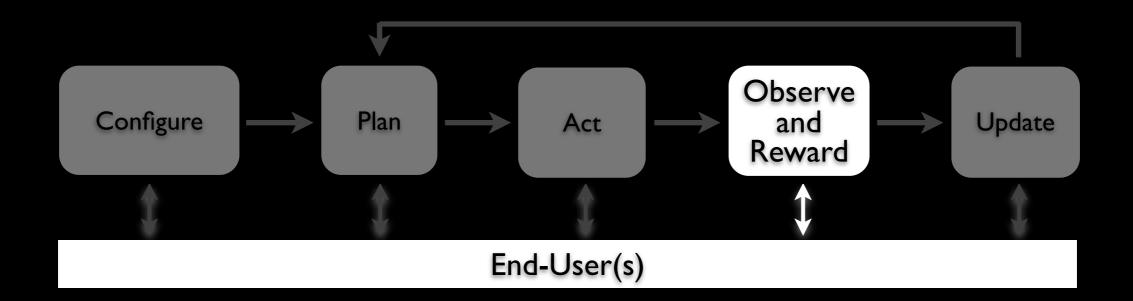
- Configuration vs. pre-configuration
- Select from a toolbox of algorithms, representations, etc.
- Possibilities for reward scaffolding



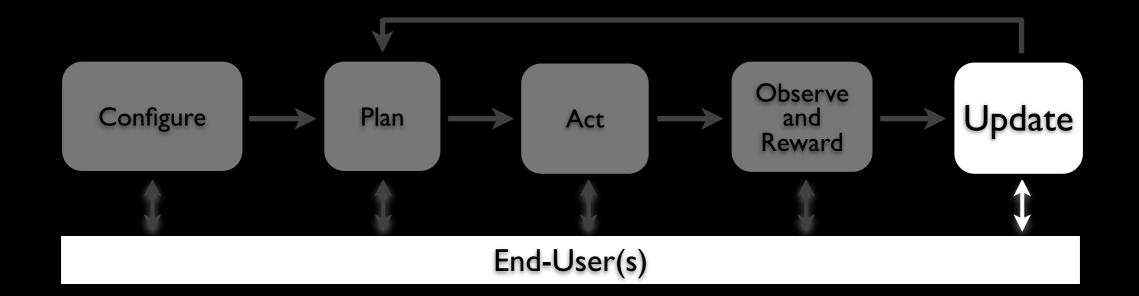
- Remove the black-box
- Replace with collaborative process
 - human and machine ask questions, give answers, make hypothesis, etc.
 - Improve utility estimates and human understanding
- Explore estimated effects of parameters and values
 - play with internal state and parameters



- Teaching by demonstration/imitation learning
- Additional benefit: improve "situation awareness"
 - (Kaber & Endsley 2004)
- Who takes control?



- Specify or "discuss" utility of outcome
 - User provides part of the reward vector
- Scaffolding
- Identify and annotate outcome



- Remove black-box, have a conversation
 - leverage human knowledge
 - improve human knowledge
- Visualization of how machine sees the world
 - Fails & Olsen, 2003
 - help user understand what machine learned

Conclusions

- A lot has been done
 - teaching by demonstration, imitation learning, reward specification
- But let's open up the box
 - Interactively determine representations, features, etc.
 - Interaction in planning, updating, configuring